## Weak maximum principle for the heat equation

Harald Hanche-Olsen

In this note, we consider the standard heat equation

$$u_t - \triangle u = 0$$
 in  $\Omega_T$ 

in which  $\Omega_T = (0, T) \times \Omega$  where  $\Omega \subset \mathbb{R}^n$  is a bounded region, T > 0, and

$$u \in C(\overline{\Omega_T}) \cap C^2(\Omega_T)$$
.

We think of  $\Omega_T$  as an open *cylinder* with base  $\Omega$  and height T. Its closure is a closed cylinder:  $\overline{\Omega_T} = [0, T] \times \overline{\Omega}$ .

**Definition.** The *parabolic boundary* of  $\Omega_T$  is the set

$$\Gamma = (\{0\} \times \overline{\Omega}) \cup ([0, t] \times \partial \Omega).$$

Clearly,  $\Gamma$  is contained in the normal boundary  $\partial \Omega_T$ ; the difference is

$$\partial \Omega_T \setminus \Gamma = \{T\} \times \Omega.$$

We call  $\{T\} \times \Omega$  the *final boundary* of  $\Omega_T$  (nonstandard nomenclature).

**Observation.** If a  $C^2$  function v has a maximum at some point in  $\Omega_T$ , then  $v_t = 0$  and  $\Delta v \leq 0$  at that point, so we get  $v_t - \Delta v \geq 0$  there. Moreover, this holds at the final boundary as well, the only difference being that there, we can only conclude  $v_t \geq 0$  and  $\Delta v \leq 0$ . In other words,

$$v_t - \triangle v \ge 0$$
 at any maximum in  $\overline{\Omega_T} \setminus \Gamma$ .

We must face a minor technical glitch: The above statement requires that v is  $C^2$  up to and including the final boundary of  $\Omega_T$ . This complicates the proof of the following theorem, but only a little.

**Theorem 1** (The weak maximum principle). Assume that  $u \in C(\overline{\Omega_T}) \cap C^2(\Omega_T)$  satisfies

$$u_t - \triangle u \le 0.$$

Then  $u(t, \mathbf{x}) \leq \max_{\Gamma} u$  for all  $(t, \mathbf{x}) \in \overline{\Omega_T}$ . In other words, u achieves its maximum on the parabolic boundary.

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*Proof.* First, to deal with the "minor technical glitch" mentioned above, we shall strengthen the assumptions somewhat, and assume that  $u \in C^2((0,T] \times \Omega)$ . We will remove this extra assumption at the end.

Now let  $\varepsilon>0$ , and put  $v(t, \boldsymbol{x})=u(t, \boldsymbol{x})-\varepsilon t$ . Then  $v_t-\triangle v\leq -\varepsilon<0$ , and so it follows *immediately* from the Observation above that v cannot achieve its maximum anywhere outside  $\Gamma$ . On the other hand, since v is continuous and  $\overline{\Omega_T}$  is compact, v does have a maximum in  $\overline{\Omega_T}$ , and so we must conclude that  $v(t, \boldsymbol{x})\leq \max_{\Gamma} v$  for any  $(t, \boldsymbol{x})\in \overline{\Omega_T}$ . But then  $u(t, \boldsymbol{x})=v(t, \boldsymbol{x})+\varepsilon t\leq \max_{\Gamma} v+\varepsilon T\leq \max_{\Gamma} u+\varepsilon T$ . Since this holds for any  $\varepsilon>0$ , it finally follows that  $u(t, \boldsymbol{x})\leq \max_{\Gamma} u$ , and the proof is complete, with the strengthened assumptions.

We now drop the requirement that  $u \in C^2((0,T] \times \Omega)$ . However, it is *still* true that  $u \in C^2((0,T'] \times \Omega)$ , for any T' < T, so the first part shows that  $u(t, \mathbf{x}) \leq \max_{\Gamma_{T'}} u$  for all  $(t, \mathbf{x}) \in \overline{\Omega_{T'}}$ . Here  $\Gamma_{T'}$  is the parabolic boundary of  $\Omega_{T'}$ . But  $\Gamma_{T'} \subset \Gamma$ , so we also have  $u(t, \mathbf{x}) \leq \max_{\Gamma} u$ . For any t < T, we can pick T' with t < T' < T, so the inequality holds. Finally, it also holds for t = T, since u is continuous on  $\overline{\Omega_T}$ . This, at last, completes the proof.

It should come as no surprise that there is also a *minimum* principle. It is proved by replacing u by -u in Theorem 1.

**Corollary 2** (The weak minimum principle). *Assume that*  $u \in C(\overline{\Omega_T}) \cap C^2(\Omega_T)$  *satisfies* 

$$u_t - \triangle u \ge 0$$
.

Then  $u(t, x) \ge \min_{\Gamma} u$  for all  $(t, x) \in \overline{\Omega_T}$ . In other words, u achieves its minimum on the parabolic boundary.

We will mostly be concerned with solutions of the heat equation  $u_t - \Delta u = 0$ , and for these, both the maximum principle and the minimum principle can be used. But we may also wish to study inhomogeneous equations  $u_t - \Delta u = f$ , and if f has a definite sign, one or the other principle will apply.

**Corollary 3** (Uniqueness for the heat equation). *There exists at most one solution*  $u \in C(\overline{\Omega_T}) \cap C^2(\Omega_T)$  *to the problem* 

$$u_t - \triangle u = f$$
 in  $\Omega_T$ ,  
 $u = g$  on  $\Gamma$ .

Here, f and g are given functions on  $\Omega_T$  and  $\Gamma$ , respectively. (Thus g combines initial values and boundary values in one function.)

*Proof.* Let u be the difference between two solutions to this problem: Then u solves the same problem, but with f = 0 and g = 0. Thus u achieves both its minimum and maximum on  $\Gamma$ , but u = 0 there, so u = 0 everywhere.

The following corollary is proved in essentially the same way, by applying the minimum and maximum principles to  $u_1 - u_2$ . Note that it immediately implies the preceding corollary by taking  $g_1 = g_2$ .

**Corollary 4** (Continuous dependence on data). Let  $u_1$  and  $u_2$  satisfy

$$u_{it} - \triangle u_i = f$$
 in  $\Omega_T$ ,  $u_i = g_i$  on  $\Gamma$ ,  $for i = 1, 2$ .

Then  $|u_1 - u_2| \le \max_{\Gamma} |g_1 - g_2|$ .

**Exercise 1** (Continuous dependence on data, improved). Assume that  $u_1$  and  $u_2$  satisfy

$$u_{it} - \triangle u_i = f_i \quad \text{in } \Omega_T, u_i = g_i \quad \text{on } \Gamma,$$
 for  $i = 1, 2$ .

Let  $\varphi = \sup_{\Omega_T} |f_1 - f_2|$  and  $\gamma = \max_{\Gamma} |g_1 - g_2|$ , and show that  $|u_1 - u_2| \le \gamma + \varphi T$ . Note that for any t, we can pick T = t, so we really get  $|u_1 - u_2| \le \gamma + \varphi t$ . Hint: Apply the maximum principle to  $u_1 - u_2 - \varphi t$  and  $u_2 - u_1 - \varphi t$ .

## **Exercise 2.** Some definitions:

The *Hessian* of u is the (symmetric!)  $n \times n$  matrix Hu with entries  $u_{x_i x_j}$ . The *Frobenius inner product* of two real matrices A and B is

$$\langle A, B \rangle_{\mathrm{F}} = \sum_{i=1}^{n} \sum_{j=1}^{n} a_{ij} b_{ij} = \mathrm{tr}(A^{T}B).$$

Show that the maximum (and minimum) principle continues to hold if  $u_t - \triangle u$  is replaced by the more general

$$u_t - \langle A, Hu \rangle_{\rm F}$$

where the real matrix A is symmetric and positive definite.

Here are some ingredients of the proof:

- At an interior maximum point, -Hu is positive semidefinite, i.e.,  $\mathbf{y}^T H \mathbf{y} \le 0$  for all  $\mathbf{y} \in \mathbb{R}^n$ . (Short proof: Take the second derivative of  $u(\mathbf{x} + s\mathbf{y})$  with respect to s where x is a maximum point, and put s = 0.)
- It is known that if A and B are positive semidefinite, then  $\langle A,B\rangle_F \geq 0$ . (Short proof: Since A is symmetric, we can write  $\langle A,B\rangle_F = \operatorname{tr}(AB)$ . A will have a positive semidefinite square root  $A^{1/2}$ . A standard result on the trace gives  $\operatorname{tr}(AB) = \operatorname{tr}(A^{1/2}A^{1/2}B) = \operatorname{tr}(A^{1/2}BA^{1/2})$ , but  $A^{1/2}BA^{1/2}$  is positive semidefinite, and such matrices have nonnegative trace.)

**Exercise 3.** Show that the maximum (and minimum) principle continues to hold if  $u_t - \triangle u$  is replaced by the even more general

$$u_t - \langle A, Hu \rangle_F + b(\nabla u),$$

where the real matrix A is symmetric and positive definite, provided b satisfies  $b(\mathbf{0}) = 0$ . (For a simple and common example, let  $b(\nabla u) = \mathbf{b} \cdot \nabla u$ .)