

Markov chain Monte Carlo (MCMC)

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Markov chain Monte Carlo

Idea

Simulate a **Markov chain** X_1, \dots, X_i, \dots , which is designed in a way such that $P(X_i = x)$ **converges to the target distribution, e.g. the posterior distribution.**

Properties:

- After convergence, one obtains random samples from the target distribution, which can be used to estimate posterior characteristics.
- Samples will typically be **dependent**.

Terminology:

- **Burn-in**: The initial samples may follow a very different distribution. These initial samples are thrown away.
- **Thinning**: Only keep every k -th iteration to save storage space.

Introduction

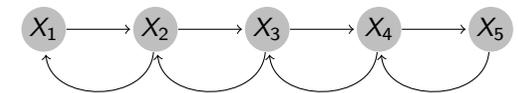
Application of ordinary Monte Carlo methods is difficult if the unknown parameter is of high dimension. However, **Markov chain Monte Carlo (MCMC) methods** will then be a useful alternative.



en.wikipedia.org/wiki/Markov_chain

Andrey Markov (1856 – 1922),
Russian mathematician.

Markov chain:



Given the previous observation X_{i-1} , X_i is independent of the sequence of events that preceded it.

Metropolis-Hastings algorithm

There is great liberty in the actual choice of the underlying random samples of MCMC algorithms.

- Random samples typically depend on the current state X_i of the Markov chain.
- Random samples are generated from some **arbitrary proposal distribution with density $Q(x_i|x_{i-1})$** , say.

The **Metropolis–Hastings algorithm** is the most general approach.

History of Metropolis-Hastings

- The algorithm was presented 1953 by Metropolis, Rosenbluth, Rosenbluth, Teller and Teller from the Los Alamos group. It is named after the first author **Nicholas Metropolis**.
- **W. Keith Hastings** extended it to the more general case in 1970.
- It was then ignored for a long time.
- Since 1990 it has been used more intensively.

Metropolis-Hastings algorithm

Metropolis-Hastings counts a rejection as an iteration and records the past value as the current value.

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1: Init  $x_0 \sim g(x_0)$ 
2: for  $i = 1$  to  $N - 1$  do
3:    $u \sim U(0, 1)$ 
4:   Generate a proposal  $x^* \sim Q(x|x_{i-1})$ 
5:   if  $u < \min \left( 1, \frac{\pi(x^*)}{\pi(x_{i-1})} \times \underbrace{\frac{Q(x_{i-1}|x^*)}{Q(x^*|x_{i-1})}}_{\text{Proposal ratio}} \right)$  then
6:      $x_i \leftarrow x^*$ 
7:   else
8:      $x_i \leftarrow x_{i-1}$ 
9:   end if
10: end for

```

Acceptance probability α

Special cases of the Metropolis-Hastings algorithm

Metropolis algorithm

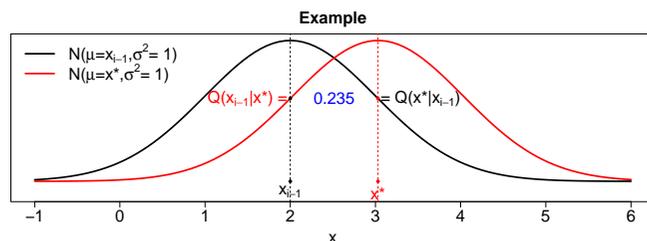
The proposal density is symmetric around the current values, that means

$$Q(x_{i-1}|x^*) = Q(x^*|x_{i-1}).$$

Hence,

$$\alpha = \min \left(1, \frac{\pi(x^*)}{\pi(x_{i-1})} \times \frac{Q(x_{i-1}|x^*)}{Q(x^*|x_{i-1})} \right) = \min \left(1, \frac{\pi(x^*)}{\pi(x_{i-1})} \right)$$

A particular case is the **random walk proposal**, defined as the current value x_{i-1} plus a random variate of a 0-centered symmetric distribution.



Remarks on the Metropolis-Hastings algorithm

- Under some regularity conditions it can be shown that the **Metropolis-Hasting algorithm converges to the target distribution** regardless of the specific choice of $Q(x|x_{i-1})$.
- However, the **speed of convergence** and the **dependence between the successive samples** depends strongly on the proposal distribution.
- Since we only need to compute the ratio $\pi(x^*)/\pi(x_{i-1})$, the **proportionality constant is irrelevant**.
- Similarly, we only care about $Q(\cdot)$ up to a constant.
- Often it is advantageous to calculate the acceptance probability on **log-scale**, which makes the computations more stable.

For more comments and details see: [Chib, S. and Greenberg, E. \(1995\), Understanding the Metropolis-Hastings algorithm, The American Statistician, 49: 327–335](#)

Special cases of the Metropolis-Hastings algorithm

Independence proposal

- The proposal distribution does not depend on the current value $\theta^{(i)}$

$$Q(x|x_{i-1}) = Q(x).$$

- **The sampler is closer to rejection sampler**. However, here if we reject, then we retain the sample.

Acceptance probability always equals unity

This is the case if

$$Q(\mathbf{x}^* | \mathbf{x}_{i-1}) = \pi(\mathbf{x}^*),$$

which seems of limited value, as direct sampling from the target density was assumed to be unavailable.

However, let $\mathbf{x} = (x^1, \dots, x^p)$ and consider updating a specific component x^j of \mathbf{x} by a sample from $\pi(x^j | \mathbf{x}^{-j})$, where \mathbf{x}^{-j} denotes \mathbf{x} without x^j . Here,

$$\pi(x^j | \mathbf{x}^{-j}) \propto \pi(\mathbf{x}), \quad j = 1, \dots, p$$

so that

$$\alpha = \min \left(1, \frac{\pi(\mathbf{x}^*)}{\pi(\mathbf{x}_{i-1})} \times \frac{\pi(x_{i-1}^j | \mathbf{x}^{-j,*})}{\pi(x_{i-1}^j | \mathbf{x}_{i-1}^{-j})} \right) = 1$$

Remarks on Gibbs sampling

- High dimensional updates of \mathbf{x} can be boiled down to scalar updates.
- **Visiting schedule:** Various approaches exist (and can be justified) to ordering the variables in the sampling loop. One approach is random sweeps: variables are chosen at random to resample.
- Gibbs sampling assumes that it is easy to sample from the full-conditional distribution. This is sometimes not so easy. Alternatively, a Metropolis-Hastings proposal can be used for the j -th component, i.e. **Metropolis-within-Gibbs**.
- **Care must be taken when improper prior are used**, which may lead to an **improper posterior distribution**. Impropriety implies that there does not exist a joint density to which the full-conditional distributions correspond.

Hobert, J. P. and Casella, G. (1996), JASA, 91: 1461–1473.

Gibbs sampling

Iterative update of all components of \mathbf{x} . Let $\mathbf{x} = (x^1, \dots, x^p)$. To obtain samples \mathbf{x}_i from the joint target distribution $p(\mathbf{x})$ do the following:

- Initialize \mathbf{x}_0 and let $i = 0$.
- Repeatedly:

Sample $x_{i+1}^1 \sim \pi(x^1 | \mathbf{x}^{-1})$

Sample $x_{i+1}^2 \sim \pi(x^2 | \mathbf{x}^{-2})$

Sample $x_{i+1}^3 \sim \pi(x^3 | \mathbf{x}^{-3})$

⋮

Sample $x_{i+1}^p \sim \pi(x^p | \mathbf{x}^{-p})$

Set $i = i+1$

It is possible to do this block-wise, i.e. sample blocks of the x^j together.

Efficiency of the Metropolis-Hastings algorithm

The efficiency and performance of the Metropolis-Hastings algorithm depends crucially on the **relative frequency of acceptance**.

An acceptance rate of one is not always good. Consider the random walk proposal:

- Too large acceptance rate \Rightarrow Slow exploration of the target density.
- Too small acceptance rate \Rightarrow Large moves are proposed, but rarely accepted.

Tuning the acceptance rate:

- For **random walk proposals**, acceptance rates between **30% and 50%** are typically recommended. They can be achieved by changing the variance of the proposal distribution.
- For **independence proposals** a **high acceptance rate** is desired, which means that the proposal density is close to the target density.