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TMA4220
Numerical Solution of
Partial Differential
Equations Using
Element Methods
Fall 2020

Solutions to exercise set 1

- 1 a) (i) Compute the $L^2([-1, 1])$ norm

$$\int_{-1}^1 (|x|^\alpha)^2 dx = 2 \int_0^1 |x|^{2\alpha} dx = \frac{2}{2\alpha + 1} [x^{2\alpha+1}]_0^1.$$

This blows up at 0 if $2\alpha + 1 < 0$. If $2\alpha + 1 = 0$ we get $\log x$, which also blows up at 0. Thus, $|x|^\alpha \in L^2([-1, 1])$ if $\alpha > -\frac{1}{2}$.

- (ii) Similarly we have

$$\int_1^\infty |x|^{2\alpha} dx = \lim_{y \rightarrow \infty} \frac{1}{2\alpha + 1} [x^{2\alpha+1}]_1^y,$$

so we need $\alpha < -1/2$.

- (iii) Transform to polar coordinates

$$\int_{B_1(0)} |x|^{2\alpha} dx = \int_0^{2\pi} \int_0^1 r^{2\alpha+1} dr d\theta,$$

and we see that the inner integral is the same integral as in (i). Thus we need $\alpha > -1$.

- b) Since D is closed and bounded and f is continuous, f takes its maximum value M on D . Then

$$\int_D f^2 dx \leq \int_D M^2 dx = M^2 \mu(D),$$

where $\mu(D)$ is the size of D .

- c) (i) Assume both v_1 and v_2 are weak derivatives of the same function u . Then, by the definition of the weak derivative

$$\int_\Omega (v_1 - v_2)\phi dx = \int_\Omega (u - u)\phi' dx = 0.$$

Hence $v_1 = v_2$ almost everywhere, i.e. equal in L^2 .

- (ii) If $u \in C^1$, we have

$$-\int u' \phi dx = \int u \phi' dx$$

by integration by parts. The boundary terms vanish since $\phi \in C_c^\infty(\Omega)$.

d) (i) Compute the two integrals as

$$\int_0^2 f_1^2 dx = \int_0^1 x^2 dx + \int_1^2 dx = 4/3 < \infty$$

$$\int_0^2 f_2^2 dx = \int_0^1 x^2 dx + \int_1^2 2 dx = 7/3 < \infty,$$

so $f_1, f_2 \in L^2$.

(ii) Compute the weak derivative of f_1 by computing

$$\begin{aligned} \int_0^2 f_1 \phi' dx &= \int_0^1 x \phi'(x) dx + \int_1^2 \phi'(x) dx \\ &= [x\phi(x)]_0^1 - \int_0^1 \phi dx + [\phi(x)]_1^2 \\ &= \phi(1) + \phi(2) - \phi(1) - \int_0^1 \phi(x) dx - \int_1^2 0\phi(x) dx. \end{aligned}$$

As $\phi(2) = 0$ since ϕ has compact support in $[0, 2]$, the weak derivative must be

$$v_1(x) = \begin{cases} 1 & \text{if } 0 < x < 1, \\ 0 & \text{if } 1 \leq x < 2, \end{cases}$$

- (ii) For f_2 we see that it is not continuous, so the weak derivative can not exist (since by the Sobolev embedding theorem $H^1 \subset C^0$). Another way to see this is to compute $\int_0^2 u \phi' dx$ and note that this will always depend on $\phi(1)$.
- (iii) To show that $f_1 \notin H^2(\Omega)$, we note that the weak derivative v_1 of f_1 is not continuous.

2 a) Using the same discrete test space X_h^1 as for the Dirichlet problem, the weak formulation becomes

$$\begin{aligned} \int_0^1 u'(x)v'(x) dx - [u'(x)v(x)]_0^1 &= \int_0^1 f v dx \\ \int_0^1 u'(x)v'(x) dx - u'(1)v(1) + u'(0)v(0) &= \int_0^1 f v dx \\ \int_0^1 u'(x)v'(x) dx &= \int_0^1 f v dx + 1 \end{aligned}$$

by inserting $v(0) = 0$, $v(1) = 1$ and $u'(1) = 1$. Then the new linear system becomes

$$Au = f + [0, \dots, 1]^T.$$

The code can then be modified by removing the boundary condition for the right end point, and adding 1 to the last element in the b-vector.

b) Integrate twice to obtain

$$\begin{aligned} u'(x) &= -x + A \\ u(x) &= -\frac{1}{2}x^2 + Ax + B. \end{aligned}$$

Use the boundary conditions

$$\begin{aligned} u(0) = 0 &\implies B = 0 \\ u'(1) = 1 &\implies A = 1 + 1 = 2 \\ u(x) &= -\frac{x^2}{2} + 2x \end{aligned}$$

- 3**
- a) False. If $v_1, v_2 \in \mathcal{S}$, then $v_1 + v_2 \notin \mathcal{S}$ since $(v_1 + v_2)(\frac{1}{2}) = 1 + 1 = 2 \neq 1$.
 - b) True. L maps elements in X to elements in \mathbb{R} , and $L(\alpha_1 v_1 + \alpha_2 v_2) = \alpha_1 L(v_1) + \alpha_2 L(v_2)$ for all $\alpha_1, \alpha_2 \in \mathbb{R}$ and all $v_1, v_2 \in X$.
 - c) False. $(x, y)_X$ is not bilinear since $(x_1 + x_2, y)_X = |x_1 + x_2||y| \neq |x_1||y| + |x_2||y|$ if x_1 and x_2 has opposite signs.
 - d) False. Use $w(x) = 1$.

- 4**
- a) Choose a test function $v \in V$, integrate by parts twice:

$$\begin{aligned} \int_0^1 u_{xxxx} v \, dx &= [u_{xxx} v]_0^1 - \int_0^1 u_{xxx} v_x \, dx \\ &= [u_{xxx} v]_0^1 - [u_{xx} v_x]_0^1 + \int_0^1 u_{xx} v_{xx} \, dx \\ &= \int_0^1 f v \, dx. \end{aligned}$$

Since $v(0) = v(1) = v_x(0) = v_x(1) = 0$, the two boundary terms vanish, and we end up with

$$a(u, v) = \int_0^1 u_{xx} v_{xx} \, dx$$

and

$$f(v) = \int_0^1 f v \, dx.$$

Then the bilinear form a is symmetric and positive since $a(v, v) = \int_0^1 v_{xx}^2 \, dx \geq 0$ with $a(v, v) = 0$ only if $v_{xx} = 0$, which implies that $v = 0$ because of the boundary conditions.

- b) $V = H_0^2((0, 1)) = \{v \in H^2((0, 1)) \mid v(0) = v(1) = v_x(0) = v_x(1) = 0\}$.