



Norwegian University of
Science and Technology

Department of Mathematical Sciences

Examination paper for
**TMA4220 Numerical Solution of Partial Differential Equations
Using Element Methods**

Academic contact during examination: Trond Kvamsdal

Phone: 93058702

Examination date: 2nd of December 2019

Examination time (from–to): 15:00–19:00

Permitted examination support material: C:

- A. Quarteroni: *Numerical Models for Differential Problems*, Springer 2014
- S. Brenner and L. R. Scott: *The Mathematical Theory of Finite Element Methods*, Springer 2008
- TMA4220 Lecture Notes Fall 2019 (Front page + 229 pages)
- TMA4220-2019H-AFEM (25 pages)
- Rottmann: *Matematisk formelsamling*
- Approved calculator

Other information:

All answers should be justified and include enough details to make it clear which methods and/or results have been used. All the (sub-)problems are worth 5 points each. The total value is 65 points.

Language: English

Number of pages: ??

Number of pages enclosed: 0

Checked by:

Informasjon om trykking av eksamensoppgave

Originalen er:

1-sidig 2-sidig

sort/hvit farger

hvit/farger

Date

Signature

Problem 1 Consider the one-dimensional Poisson equation

$$-u_{xx} = f \quad \text{in } \Omega \quad (1)$$

with the boundary conditions

$$u = 0 \quad \text{on } \partial\Omega_D \quad (2)$$

$$H(u) = \bar{t} \quad \text{on } \partial\Omega_N. \quad (3)$$

where u is the unknown solution, f the applied loading and \bar{t} are prescribed Neumann boundary conditions for the given Poisson problem defined on the interval $\Omega \in R^1$. The differential operator $H(u)$ is the so called “Neumann operator”.

- a) Use Galerkin’s method and establish the weak formulation corresponding to the problem (??)-(??) on the form: Find $u \in X$ such that

$$a(u, v) = l(v) \quad \forall v \in X \quad (4)$$

In particular, identify X , a and l for this problem. Identify also the expression for the “Neumann operator” $H(u)$ related to the Neumann boundary conditions.

- b) Assume that we choose the finite element method to solve (??) numerically. Formulate the corresponding finite element variational formulation.
- c) Establish the linear algebraic system of equations in the form: $\mathbf{A}\mathbf{x} = \mathbf{b}$, where \mathbf{A} is the system coefficient matrix (also denoted “stiffness matrix”), \mathbf{x} is the vector of unknown nodal coefficients and \mathbf{b} is the right hand side due to applied loading and prescribed boundary conditions given in (??)-(??).
- d) Introduce quadratic Lagrange nodal basis functions to express the finite element solution u_h and the corresponding test function v_h for the finite element variational problem above. Compute the coefficient matrix (“element stiffness matrix”) \mathbf{A}_e for one quadratic Lagrange 1D-element (line element with three nodes).
- e) Compute the system coefficient matrix \mathbf{A} for the above finite element Poisson problem where $\Omega = (0, 1)$, $\partial\Omega_D = \{x = 0\}$ and $\partial\Omega_N = \{x = 1\}$ that is discretized with three quadratic Lagrange 1D-elements of equal length.

Problem 2

- a) What characterize a finite element? What is a compatible finite element?
- b) Define a compatible quartic (i.e. 4th order) triangular Lagrange type finite element, i.e. show the nodal locations. Verify that your quartic triangular finite element fulfils the conditions necessary to construct a compatible finite element space.
- c) Define "affine coordinate mapping". Which property inherent in affine coordinate mappings is consider to be of special interest related to the finite element method.
- d) Define the nodal basis functions for the 5 node "transfer element" shown in Figure 1, such that it is compatible with neighbouring standard 9 node quadratic Lagrange quadrilateral element along the edge with the midpoint node, and compatible with a neighbouring 4 node linear Lagrange quadrilateral element along each of the other edges.

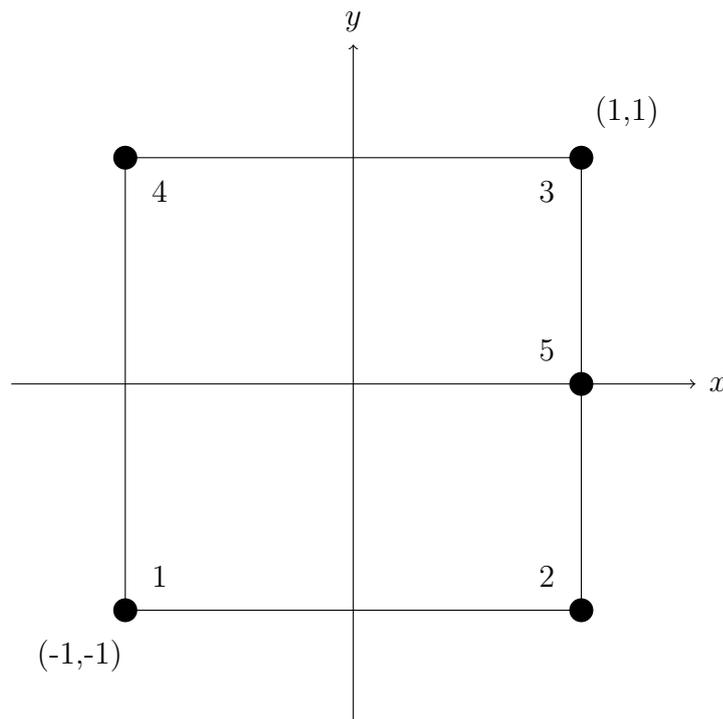


Figure 1: "Transfer element" with 5 nodes

Problem 3 Here we again consider a one-dimensional Poisson problem as described in Problem 1, i.e., Equation (1)–(3) with the weak formulation as given in Equation (4) to be solved with a corresponding compatible finite element problem using the finite dimensional space X_h .

- a) What is the superconvergence property? What are the conditions for it to be present?
- b) State the three conditions for the recovery operator G_{x_h} that is sufficient to guarantee that $G_{x_h}(I_{x_h}u)$ is a good approximation to the true gradient ∇u . Here I_{x_h} is the interpolant operator on the finite element space X_h .
- c) Construct a recovery operator G_{x_h} that fulfills the three conditions found in 3(b) for one-dimensional linear finite elements. Check that your recovery operator is *consistent*.
- d) Describe how you can utilise the recovered gradient $G_{x_h}(u_h)$ to estimate the error in the numerically computed finite element solution $u_h \in X_h$.