



- 1 Consider the following heat equation on  $x \in [0, 1]$ ,

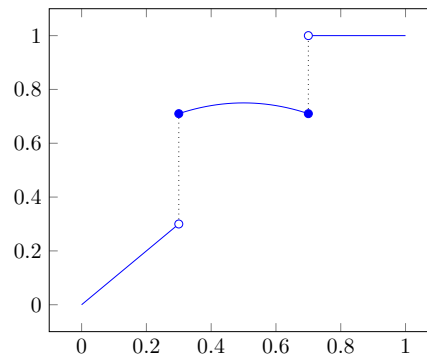
$$u_t = u_{xx}, \quad u(0, t) = u(1, t) = 0, \quad u(0, x) = \begin{cases} 2x, & 0 \leq x \leq 1/2, \\ 2 - 2x, & 1/2 \leq x \leq 1, \end{cases}$$

for  $t > 0$  as we considered in Section 4.2.

- a) Implement the Crank-Nicolsons method on your computer. Since this is a voluntary exercise, use any language you like. If you choose to use Matlab, the code is given in Section 4.2.4. Observe time evolution of the solution. When time  $t$  is sufficiently large, how the solution look like?

**[Solution]** When time is sufficiently large, the solution converges to zero. Look at the first animation in the supplementary file.

- b) The heat equation is known to have smoothing property: even if the initial condition is discontinuous (but in  $L_2$ ), the solution at any  $t > 0$  is in  $C^\infty$ . Check this property numerically by choosing your own discontinuous initial condition.



**[Solution]** Look at the second animation in the supplementary file.

- c) Modify your code for a general  $\theta$  method, and compare the numerical solution (your choice of  $\theta \neq 1/2$ ) with the Crank-Nicolsons method. Draw the convergence plot (in terms of  $M$ ) of this method using as if the Crank-Nicolsons method is the analytic solution, where both methods should use the same number of points  $M$ . Theoretically, what convergence rate do you expect? And do you numerically see it?

**[Solution]** For  $M$  large enough, the error difference between first order 1 method ( $\theta \neq 1/2$ ) and order 2 method (Crank-Nicolson) is  $\mathcal{O}(M^{-1}) - \mathcal{O}(M^{-2}) = \mathcal{O}(M^{-1})$ , therefore we expect the first order convergence and you should actually see it numerically.

d) Consider a modified problem

$$u_t = -u_{xx},$$

with the same boundary/initial conditions. This is known to be an ill-posed problem where the solution diverges analytically. Consider the  $\theta$  method to numerically solve this problem. Prove that you cannot obtain  $F$ -stability with any choice of parameters (Hint: look at Section 5.5).

**[Solution]** Write the linear system in the following manner (look at Section 5.5):

$$(I + \theta rS)\mathbf{U}^{n+1} = ((I + (\theta - 1)rS)\mathbf{U}^n + \mathbf{d}^n,$$

where  $S$  is the same as Section 5.5, and our boundary condition is expressed in  $\mathbf{d}^n$ . Note that because of the modified problem, the sign before the matrix  $S$  is now different. We want to prove that

$$\rho((I + \theta rS)^{-1}(I - (1 - \theta)rS)) > 1.$$

Now let

$$A := (I + \theta rS) = \text{tridiag}(r\theta, 1 - 2r\theta, r\theta),$$

$$B = (I - (1 - \theta)rS) = \text{tridiag}(-r(1 - \theta), 1 + 2r(1 - \theta), -r(1 - \theta)).$$

We know that (e.g., look at the previous exercise) for a tridiagonal matrix  $\text{tridiag}(c, a, b)$  the eigenvectors  $\mathbf{x}^{(k)}$  and the associated eigenvalues  $\lambda_k$  are given by

$$x_j^{(k)} = \left(\frac{b}{c}\right)^{j/2} \sin\left(\frac{jk\pi}{M+1}\right), \quad \lambda_k = a + 2\sqrt{bc} \cos\left(\frac{k\pi}{M+1}\right),$$

where  $x_j^{(k)}$  is the  $j$ th element of the vector  $\mathbf{x}^{(k)}$ ;  $A\mathbf{x}^{(k)} = \lambda_k\mathbf{x}^{(k)}$ . Observe that  $A$  and  $B$  have the same eigenvectors. This means we can diagonalize  $A$  and  $B$  by the same orthogonal matrix  $T$ :

$$A = T\Lambda_A T^{-1}, \quad B = T\Lambda_B T^{-1},$$

where  $\Lambda_A$  and  $\Lambda_B$  are diagonal matrices consisting of eigenvalues of  $A$  and  $B$ , respectively. Therefore,

$$(I + \theta rS)^{-1}(I - (1 - \theta)rS) = A^{-1}B = T\Lambda_A^{-1}\Lambda_B T^{-1}.$$

So the eigenvalues of  $A^{-1}B$  is

$$\frac{\lambda_{B,k}}{\lambda_{A,k}} = \frac{1 + 2(1 - \theta)r + 2(1 - \theta)r \cos(k\pi/(M + 1))}{1 - 2\theta r + 2\theta r \cos(k\pi/(M + 1))},$$

for  $k = 1, \dots, M$ . With easy calculation one can show

$$\forall k \frac{\lambda_{B,k}}{\lambda_{A,k}} \geq 1, \quad \text{and, } \exists k \frac{\lambda_{B,k}}{\lambda_{A,k}} > 1.$$

Therefore,

$$\rho(A^{-1}B) > 1.$$

**2** Solve the problems 3, 4 and 5 of the exercise 1 from 2020.

**[Solution]** Solution is given here.