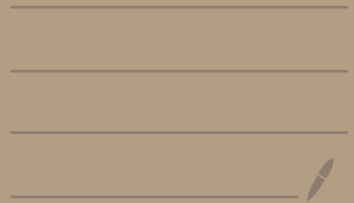


Optimization II

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2. Finite-dim. Case

admissible set $U_{ad} \subset \mathbb{R}^m$

closed, bounded, convex

$A \in \mathbb{R}^{n, n}$ regular, rank n

$B \in \mathbb{R}^{n, m}$ $m \leq n$

• state equation $Ay = Bu$ (SE)

• $y \in \mathbb{R}^n$ state

• $u \in \mathbb{R}^m$ control

• cost functional

$$J(y, u) = \frac{1}{2} \underbrace{|y - y_d|^2}_{\text{tracking}} + \frac{\gamma}{2} \underbrace{|u|^2}_{\text{regularization}}$$

y_d desired state

$$\begin{aligned}
 (\text{CP}) \quad & \min J(y, u) \\
 & \text{subject to } Ay = Bu \quad (\text{SE}) \\
 & \text{and } u \in \mathcal{U}_{ad} \quad \text{control constr.}
 \end{aligned}$$

$$A \text{ regular} \Rightarrow y = A^{-1}Bu$$

$$\begin{aligned}
 \text{define } S: \mathbb{R}^m &\rightarrow \mathbb{R}^n \quad u \mapsto y(u) \\
 & \text{solution operator}
 \end{aligned}$$

$$\text{here: } S = A^{-1}Bu$$

now, consider reduced cost functional

$$f(u) = J(y(u), u) = \frac{1}{2} \|Su - y_d\|^2 + \frac{\delta}{2} \|u\|^2$$

$$(\text{CP}) \Leftrightarrow \boxed{\begin{aligned} & \min f(u) \\ & u \in \mathcal{U}_{ad} \end{aligned}} \quad (\tilde{\text{CP}})$$

Q1: Existence of sol. to (CP)

f continuous, \mathcal{U}_{ad} compact

Weierstrass theorem $\Rightarrow \exists$ sol. to (CP)

Q2: Optimality conditions

let $\bar{u} \in \mathcal{U}_{ad}$ is a sol to (CP)

take $u \in \mathcal{U}_{ad}$ then

$$\bar{u} + t(u - \bar{u}) = tu + (1-t)\bar{u} \in \mathcal{U}_{ad}$$

for $t \in [0, 1]$

$$\lim_{t \rightarrow 0} \frac{f(\bar{u} + t(u - \bar{u})) - f(\bar{u})}{t} \geq 0 \quad \text{for } t \in [0, 1]$$

$$\nabla f(\bar{u})^T (u - \bar{u}) \geq 0 \quad \forall u \in \mathcal{U}_{ad}$$

$$\text{recall } f(u) = \frac{1}{2} \|Su - \gamma_d\|^2 + \frac{\gamma}{2} \|u\|^2$$

$$\frac{\partial f}{\partial u_k} = \frac{\partial}{\partial u_k} \left(\frac{1}{2} \sum_{i=1}^m [Su - \gamma_d]_i^2 \right) + \frac{\gamma}{2} \frac{\partial}{\partial u_k} \sum_{i=1}^m u_i^2$$

$$= \sum_{i=1}^m [Su - \gamma_d]_i \underbrace{\frac{\partial}{\partial u_k} \left(\sum_{i=1}^m S_{ij} u_j \right)}_{S_{ik} = S_{ki}^T} + \gamma u_k$$

$$= [S^T (Su - \gamma_d)]_k + \gamma u_k$$

$$\Rightarrow \nabla f(u) = S^T (Su - \gamma_d) + \gamma u$$

since $S = A^{-1}B$, we get

$$\nabla f(u) = B^T \underbrace{(A^T)^{-1} (\gamma - \gamma_d)}_{=: p} + \gamma u$$

to simplify the expression, we

introduce $p = (A^T)^{-1} (\gamma - \gamma_d)$

the adjoint state, and

$$A^T p = \gamma - \gamma_d \quad (\text{adjoint equation})$$

Theorem 1: let \bar{u} be a sol. to (CP)

then, there exists an adj. state p s.t.

$$(1) \quad A \bar{\gamma} = B \bar{u} \quad (SE)$$

$$(2) \quad A^T p = \bar{\gamma} - \gamma_d \quad (AE)$$

$$(3) \quad \underbrace{\langle B^T p + \gamma \bar{u}, u - \bar{u} \rangle}_{\nabla f(\bar{u})} \geq 0 \quad \forall u \in U_{ad}$$

• Introduce Lagrangian

$$\mathcal{L}(\gamma, p, u) = J(\gamma, u) - \langle A\gamma - Bu, p \rangle$$

$$= \frac{1}{2} |\gamma - \gamma_d|^2 + \frac{\alpha}{2} |u|^2 - \langle A\gamma - Bu, p \rangle$$

$$\mathcal{L}_y = y - y_d - A^T p \stackrel{!}{=} 0 \rightsquigarrow (AE)$$

$$\mathcal{L}_p = -(Ay - Bu) \stackrel{!}{=} 0 \rightsquigarrow (SE)$$

$$\mathcal{L}_u = \gamma u + B^T p$$

In other words $\mathcal{L}_p(\bar{y}, \bar{p}, \bar{u}) = 0$ (SE)

$$\mathcal{L}_y(\bar{y}, \bar{p}, \bar{u}) = 0$$
 (AE)

$$\langle \mathcal{L}_u(\bar{y}, \bar{p}, \bar{u}), u - \bar{u} \rangle \geq 0 \quad (\forall I)$$

Box constraints and KKT conditions

$$\mathcal{U}_{ad} = \{ u \in \mathbb{R}^m \mid u^a \leq u \leq u^b \}$$

with $u^a \leq u^b$ and $u^a, u^b \in \mathbb{R}^m$

to be understood component wise, i.e.

$$u_i^a \leq u_i \leq u_i^b, \quad 1 \leq i \leq m$$

$$\begin{aligned}
 (\text{CP}) \quad & \min f(u) \\
 \text{s.t.} \quad & c^1(u) = u - u^a \geq 0 \\
 & c^2(u) = u^b - u \geq 0
 \end{aligned}
 \left. \vphantom{\begin{aligned} \text{s.t.} \\ c^1(u) \\ c^2(u) \end{aligned}} \right\} \begin{array}{l} 2m \\ \text{ineq.} \end{array}$$

LICQ (Linear indep. constraint qualid.)

$$\{ \nabla c_i, i \in A(\bar{u}) \} \text{ l.i.}$$

$$\frac{\partial c_i^1}{\partial u_k} = \delta_{ik} \quad \frac{\partial c_i^2}{\partial u_k} = -\delta_{ik}$$

we can have at most $\begin{pmatrix} \pm 1 & & 0 \\ & \ddots & \\ 0 & & \pm 1 \end{pmatrix}$

\Rightarrow (LICQ) holds

introduce Lagr.

$$\begin{aligned}
 \mathcal{L}(u, \mu^a, \mu^b) = & f(u) - \langle \mu^a, u - u^a \rangle \\
 & - \langle \mu^b, u^b - u \rangle
 \end{aligned}$$

i) compute Lagrangian multipliers

$$\nabla_u \mathcal{L}(\bar{u}, \mu^a, \mu^b) = 0 = \nabla f(\bar{u}) - \mu^a + \mu^b$$

$$\Rightarrow \frac{\partial f}{\partial u_k} = \mu_k^a - \mu_k^b \quad \text{and}$$

$$\mu^a \text{ and } \mu^b \geq 0$$

$$\frac{\partial f}{\partial u_k} \geq 0 \Rightarrow \mu_k^a = \frac{\partial f}{\partial u_k}$$

$$\mu_k^b = 0$$

$$\frac{\partial f}{\partial u_k} \leq 0 \Rightarrow \mu_k^a = 0$$

$$\mu_k^b = -\frac{\partial f}{\partial u_k}$$

$$\mu^a = [\nabla f(\bar{u})]_+ \quad \mu^b = [\nabla f(\bar{u})]_-$$

where $[x]_+ = \max\{0, x\}$

$$[x]_- = -\min\{0, x\}$$

and $x = [x]_+ - [x]_-$

(ii) Complementarity conditions

exploit var. inequ.

$$\langle \nabla f(\bar{u}), \tilde{u} - \bar{u} \rangle \geq 0 \quad \forall \tilde{u} \in U_{ad}$$

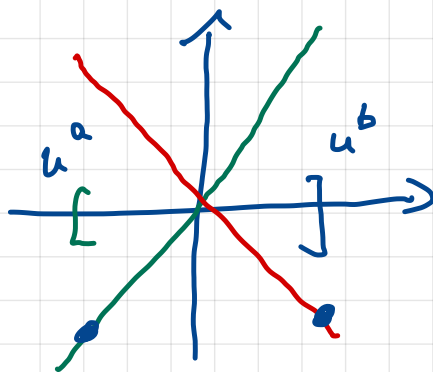
$$\tilde{u}_i = \begin{cases} \bar{u}_i, & \text{for } i \neq k \\ u, & \text{for } i = k \end{cases} \in U_{ad}$$

$$\frac{\partial f(\bar{u})}{\partial u_k} (u - \bar{u}_k) \geq 0 \quad \forall u \in [u_k^a, u_k^b]$$

$$\Leftrightarrow \frac{\partial f(\bar{u})}{\partial u_k} \bar{u}_k \leq \frac{\partial f(\bar{u})}{\partial u_k} u \quad \forall u \in [u_k^a, u_k^b]$$

$$\Leftrightarrow \frac{\partial f(\bar{u})}{\partial u_k} \bar{u}_k = \min_{u \in [u_k^a, u_k^b]} \frac{\partial f(\bar{u})}{\partial u_k} u$$

$$\Leftrightarrow \bar{u}_k = \begin{cases} u_k^a & \text{if } \frac{\partial f}{\partial u_k} > 0 \\ u_k^b & \text{if } \frac{\partial f}{\partial u_k} < 0 \end{cases}$$



now, consider compl. cond.:

$$\mu_k^a (\bar{u}_k - u_k^a) = 0$$

$$\text{if } \bar{u}_k > u_k^a \stackrel{(*)}{\implies} \frac{\partial f(\bar{u})}{\partial x_k} \leq 0$$

$$\implies \mu_k^a = 0$$

$$\text{if } \mu_k^a > 0 \implies \frac{\partial f(\bar{u})}{\partial u_k} > 0$$

$$\stackrel{(*)}{\implies} \bar{u}_k = u_k^a$$

\implies complement. cond. holds,
all in all, we have shown

Theorem 2: If \bar{u} is sol. to (P) with
box contr., with p adj. state, A regular,
then there exist Lagr. multipliers μ^a, μ^b
satisfying

$$\nabla_{\gamma} \mathcal{L}(\bar{\gamma}, \bar{u}, \bar{P}, \mu^a, \mu^b) = 0$$

$$\nabla_u \mathcal{L}(\bar{\gamma}, \bar{u}, \bar{P}, \mu^a, \mu^b) = 0$$

$$\mu^a \geq 0, \quad \mu^b \geq 0$$

$$\langle u^a - \bar{u}, \mu^a \rangle = \langle \bar{u} - u^b, \mu^b \rangle = 0$$