



Weierstrass Institute for  
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# Optimization II

## – basic facts from functional analysis

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- Notation – Multiindices

$$\alpha = (\alpha_1, \dots, \alpha_n), \quad \alpha_i \in \mathbb{N}_0$$

$$|\alpha| = \sum_{i=1}^n \alpha_i, \quad x^\alpha = x_1^{\alpha_1} \cdot \dots \cdot x_n^{\alpha_n}, \quad x \in \mathbb{R}^n$$

$$D^\alpha \phi = \left( \frac{\partial}{\partial x} \right)^\alpha \phi = \left( \frac{\partial}{\partial x_1} \right)^{\alpha_1} \dots \left( \frac{\partial}{\partial x_n} \right)^{\alpha_n} \phi$$

- **Motivation:** Let  $y \in C^1[0, 1]$  and  $\phi \in C_0^\infty(0, 1)$ , then

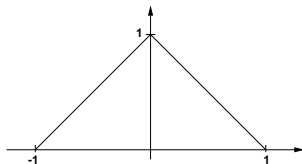
$$\int_0^1 y' \phi dx = - \int_0^1 y \phi' dx + \underbrace{y \phi \Big|_0^1}_{=0} = - \int_0^1 y \phi' dx$$

- Definition

$y \in L^1_{loc}(\Omega)$  has a weak derivative  $D^\alpha y$ , if there exists a function  $g \in L^1_{loc}(\Omega)$  such that

$$\int_{\Omega} g(x)\phi(x)dx = (-1)^{|\alpha|} \int_{\Omega} y(x)\phi^{(\alpha)}(x)dx \quad \text{for all } \phi \in C_0^\infty(\Omega).$$

Then  $g = D^\alpha y$  is called weak derivative of  $y$ .



- **Example:** Let  $f(x) = 1 - |x|$  then  $f$  is weakly differentiable with derivative

$$g(x) = \begin{cases} 1, & x < 0 \\ -1, & x > 0 \end{cases}.$$

- **Proof:**

$$\begin{aligned} \int_{-1}^1 f(x)\phi'(x)dx &= \int_{-1}^0 (1+x)\phi'(x)dx + \int_0^1 (1-x)\phi'(x)dx \\ &= - \int_{-1}^0 \phi(x)dx + f\phi \Big|_{-1}^0 + \int_0^1 \phi(x)dx + f\phi \Big|_0^1 \\ &= - \int_{-1}^1 g(x)\phi(x)dx. \end{aligned}$$

- Definition

$$H^m(\Omega) = \{u \in L^2(\Omega) \mid \partial^\alpha u \in L^2(\Omega) \text{ for all } \alpha \text{ with } |\alpha| \leq m\}$$

- Remark  $H$  is a Hilbert space with scalar product

$$(u, v)_{m, \Omega} = \sum_{0 \leq |\alpha| \leq m} \int_{\Omega} \partial^\alpha u(x) \partial^\alpha v(x) dx$$

- Important case:

$$H^1(\Omega) = \{u \mid (u, u)_{1, \Omega}^{1/2} < \infty\}$$

with scalar product

$$(u, v)_{1, \Omega} = \int_{\Omega} uv dx + \int_{\Omega} \nabla u \cdot \nabla v dx$$

and norm

$$\|u\|_{H^1(\Omega)} = (u, u)_{1, \Omega}^{1/2} = \left( \int_{\Omega} u^2 dx + \int_{\Omega} |\nabla u|^2 dx \right)^{1/2}$$

- **Theorem** Let  $\Omega \subset \mathbb{R}^n$  a domain with Lipschitz boundary, then there holds
  - $H^s(\Omega) \subset C^k(\bar{\Omega})$ , if  $s > k + \frac{n}{2}$ .
  - For  $s > k + \frac{n}{2}$  there exists a constant  $C > 0$ , such that

$$\|u\|_{C^k(\bar{\Omega})} \leq C \|u\|_{H^s(\Omega)} \quad (\text{continuous embedding}).$$

- The embedding is even compact.
- **Examples**
  - $n = 1$ , i.e.,  $\Omega = (a, b)$ ,  $s = 1 > 0 + \frac{1}{2}$  then

$$H^1(a, b) \subset C[a, b]$$

- $n = 2$ ,  $s = 1 \not> 0 + 1$  no continuous embedding of  $H^1(\Omega)$  in  $C(\bar{\Omega})$ .
- $n = 3$ ,  $s = 2 > 0 + \frac{3}{2}$ , hence  $H^2(\Omega) \hookrightarrow C(\bar{\Omega})$ .

- Theorem

Let  $\Omega \subset \mathbb{R}^n$  be a Lipschitz domain, then there exists a linear, surjective, continuous mapping (the trace operator)

$$T : H^1(\Omega) \rightarrow L^2(\partial\Omega)$$

with

$$Tu = u|_{\partial\Omega}$$

and there exists a constant  $C > 0$  such that

$$\|u\|_{L^2(\partial\Omega)} \leq C \|u\|_{H^1(\Omega)} .$$

- Important case:

$$H_0^1(\Omega) = \{v \in H^1(\Omega) \mid T(v) = v|_{\partial\Omega} = 0\}$$

- **Lemma** Let  $\Omega$  be an open Lipschitz domain and  $\Gamma_1 \subset \partial\Omega$  measurable with  $|\Gamma_1| > 0$ . Then there exists a constant  $c$  independent of  $y \in H^1(\Omega)$ , such that

$$\|y\|_{H^1(\Omega)}^2 \leq c \left( \int_{\Omega} |\nabla y|^2 dx + \int_{\Gamma_1} y^2 ds \right).$$



- Theorem

Let  $\Omega \subset \mathbb{R}^n$  be a Lipschitz domain and  $u, v \in H^1(\Omega)$ . Then, there holds

$$\int_{\Omega} u(x) \partial_i v(x) dx = - \int_{\Omega} \partial_i u(x) v(x) dx + \int_{\partial\Omega} u(s) v(s) \nu_i(s) ds$$

for  $1 \leq i \leq n$ , where  $\nu_i$  is the  $i$ -th component of the outer normal  $\nu$ .

- **Definition** Let  $a(\cdot, \cdot) : V \times V \rightarrow \mathbb{R}$  be a bilinear form on a normed linear space  $V$ .

- It is called bounded (or continuous), if there exists a  $C > 0$  such that

$$|a(v, w)| \leq C \|v\|_V \|w\|_V \quad \text{for all } v, w \in V$$

- It is called coercive, if there exists an  $\alpha > 0$  such that

$$a(v, v) \geq \alpha \|v\|_V^2 \quad \text{for all } v \in V.$$

- **Theorem (Lax-Milgram)** Let  $(V, (\cdot, \cdot))$  be a Hilbert space,  $a(\cdot, \cdot)$  a coercive and continuous bilinear form and  $F \in V^*$  (i.e., a linear, continuous mapping  $V \rightarrow \mathbb{R}$ ), then there exists one and only one  $y \in V$  such that

$$a(y, v) = F(v) \quad \text{für alle } v \in V.$$

- **Equivalence of boundedness and continuity**

A linear operator between normed spaces is bounded if and only if it is continuous.

- **Riesz Representation Theorem** If  $X$  is a Hilbert space, then

$$J(x)(y) := (y, x)_X \quad \text{for } x, y \in X$$

defines an isometric linear isomorphism  $J : X \rightarrow X'$ .

- **Young's Inequality**

For  $\delta > 0$  and real numbers  $a, b$ , there holds

$$ab \leq \delta a^2 + \frac{1}{4\delta} b^2$$

- **Hölder's Inequality**

Let  $p, q \in [1, \infty]$  with  $\frac{1}{p} + \frac{1}{q} = 1$ , then there holds

$$\|fg\|_{L^1(\Omega)} \leq \|f\|_{L^p(\Omega)} \|g\|_{L^q(\Omega)}.$$