

Optimization II

Lecture 6

Thursday, Feb. 3

Theorem 3.11 let $\gamma_d \in L^2(\Omega)$, $\gamma \geq 0$,
and $\mathcal{U}_{ad} \subset L^2(\Omega)$, closed, convex and
bounded. Then, (CPI) has a unique
sol. $\bar{u} \in \mathcal{U}_{ad}$.

Proof: (i) Existence of an opt. control

$$\text{let } l = \inf_{u \in \mathcal{U}_{ad}} J(\gamma(u), u)$$

and $\{u_n\} \subset \mathcal{U}_{ad}$ s.th.

$$J(\gamma(u_n), u_n) \rightarrow l$$

\mathcal{U}_{ad} is bounded

$\xRightarrow{\text{Lemma 3.16}}$

\exists subsequence $\{u_{n_i}\}$

$u_{n_i} \rightharpoonup \bar{u}$ weakly in $L^2(\Omega)$

$\xRightarrow{\text{Lemma 3.8}}$

$\bar{u} \in \mathcal{U}_{ad}$

Let $\gamma_n = S(u_n)$ sol. to (SE), i.e.

$$\int_{\Omega} \nabla \gamma_n \cdot \nabla \varphi \, dx = \int_{\Omega} u_n \cdot \varphi \, dx \quad \forall \varphi \in H_0^1(\Omega)$$

Take $\varphi = \gamma_n$ and derive a priori estimate:

$$\|\gamma_n\|_{H^1(\Omega)}^2 \leq \int_{\Omega} |\nabla \gamma_n|^2 \, dx = \int_{\Omega} u_n \gamma_n \, dx$$

$$\leq \|u_n\|_{L^2(\Omega)} \underbrace{\|\gamma_n\|_{L^2(\Omega)}}_{\leq \|\gamma_n\|_{H^1(\Omega)}}$$

$$\Rightarrow \|\gamma_n\|_{H^1(\Omega)} \leq \|u_n\|_{L^2(\Omega)} \leq C$$

C indep. of n .

lemma 3.10

\Rightarrow \exists subseq. $\{\gamma_{n_k}\}$

$$\text{s.t. } \gamma_{u_n} \rightarrow \bar{\gamma} \text{ in } H_0^1(\Omega)$$

now, we show that $\bar{\gamma} = S(\bar{u})$

to this end, go back to weak form.

$$\int_{\Omega} \nabla \gamma_{u_n} \cdot \nabla \varphi \, dx = \int_{\Omega} u_{u_n} \varphi \, dx$$



$$\int_{\Omega} \nabla \bar{\gamma} \cdot \nabla \varphi \, dx = \int_{\Omega} \bar{u} \varphi \, dx \quad \forall \varphi \in H_0^1(\Omega)$$

$$(L u) \Rightarrow \bar{\gamma} = S \bar{u}$$

$J(\gamma(u), u)$ is convex

lemma 3.9

\Rightarrow

$$\begin{aligned} f(\bar{u}) &\leq \liminf_{n \rightarrow \infty} f(u_{u_n}) = l \\ &= \inf J(\gamma(u), u) \end{aligned}$$

$\Rightarrow \bar{u}$ is an optimal control
with optimal state $\bar{y} = S(\bar{u})$

(ii) uniqueness

we know,

$$(*) \quad \left[\frac{1}{2}(a+b) \right]^2 < \frac{1}{2}a^2 + \frac{1}{2}b^2$$

for $a \neq b$

assume $\bar{u}_1 \neq \bar{u}_2 \in \mathcal{U}_{ad}$ are sol.
to (CPI) and define

$$\bar{u} = \frac{1}{2}\bar{u}_1 + \frac{1}{2}\bar{u}_2 \quad \text{then}$$

$$\begin{aligned} J(\bar{u}) &= \frac{1}{2} \int_{\Omega} \left(S\left(\frac{1}{2}\bar{u}_1 + \frac{1}{2}\bar{u}_2\right) - \gamma_d \right)^2 dx \\ &\quad + \frac{1}{2} \int_{\Omega} \left(\frac{\bar{u}_1}{2} + \frac{\bar{u}_2}{2} \right)^2 dx \end{aligned}$$

S linear

$$= \frac{1}{2} \int_{\Omega} \left[\frac{1}{2}(S(u_1) - \gamma_d) + \frac{1}{2}(S(u_2) - \gamma_d) \right]^2 dx$$

$$+ \frac{\delta}{2} \int_{\Omega} \left(\frac{\bar{u}_1}{2} + \frac{\bar{u}_2}{2} \right)^2 dx$$

$$(*) \quad \leftarrow \frac{1}{2} \underbrace{f(\bar{u}_1)}_{=l} + \frac{1}{2} \underbrace{f(\bar{u}_2)}_{=l} = l$$

contradiction $\Rightarrow \bar{u}_1 = \bar{u}_2$.

Remarks:

(1) The convention remains true, if $\Omega_{ad} = L^2(\Omega)$ and $\delta > 0$, then there holds

$$(*) \quad \begin{aligned} J(\gamma, u) &= \frac{1}{2} \int_{\Omega} (\gamma - \gamma_d)^2 dx + \frac{\delta}{2} \int_{\Omega} u^2 dx \\ &\geq \frac{\delta}{2} \int_{\Omega} u^2 dx = \frac{\delta}{2} \|u\|_{L^2(\Omega)}^2 \end{aligned}$$

In the proof, take minimizing sequence then bound for $\{u_n\}$

comes from (*).

(2) Uniqueness can be proved for any strictly convex cost function.

Corollary 3.12

Let $W_{ad} \subset L^2(\partial\Omega)$ closed, bounded and convex. Then, (CP2) has a unique solution $\bar{w} \in W_{ad}$.