



1 Consider the quadratic function

$$f(x) = \frac{1}{2}x^T Qx - b^T x$$

with  $Q \in \mathbb{R}^{d \times d}$  symmetric and positive definite and  $b \in \mathbb{R}^d$ .

- a) Compute the gradient and the Hessian of the function  $f$ , verify that  $f$  is strictly convex, and find the unique global minimum of  $f$ .
- b) Let  $x \in \mathbb{R}^d$ , and let  $p \in \mathbb{R}^d$  be a direction satisfying the inequality  $\nabla f(x)^T p < 0$ . Compute analytically the step length  $\alpha_{x,p}$  that solves the (exact) line search problem  $\min_{\alpha > 0} f(x + \alpha p)$ .
- c) Let  $x, p \in \mathbb{R}^d$ , and  $\alpha_{x,p}$  be as in the previous question. Show that the step length  $\alpha_{x,p}$  satisfies the strong Wolfe conditions if and only if  $c_1 \leq 1/2$ .

2 Cf. the exam 2016.

A function  $f: \mathbb{R}^d \rightarrow \mathbb{R}$  is called *strongly convex*,<sup>1</sup> if there exists  $c > 0$  such that the function  $x \mapsto f(x) - \frac{c}{2}\|x\|^2$  is convex.

- a) Show that a twice differentiable function  $f: \mathbb{R}^d \rightarrow \mathbb{R}$  is strongly convex, if and only if there exists  $c > 0$  such that

$$p^T \nabla^2 f(x) p \geq c \|p\|^2$$

for all  $p \in \mathbb{R}^d$  and  $x \in \mathbb{R}^d$ .

Verify that this is equivalent to the condition that all the eigenvalues of all the matrices  $\nabla^2 f(x)$ ,  $x \in \mathbb{R}^d$ , are larger or equal to  $c$ .

- b) Assume that  $f: \mathbb{R}^d \rightarrow \mathbb{R}$  is twice continuously differentiable and strongly convex, and assume that  $x^*$  is a minimiser of  $f$ . Show that there exists  $c > 0$  such that

$$f(x) \geq f(x^*) + \frac{c}{2}\|x - x^*\|^2$$

for every  $x \in \mathbb{R}^d$ .

- c) Show that every strongly convex and continuously differentiable function  $f: \mathbb{R}^d \rightarrow \mathbb{R}$  has a minimizer  $x^* \in \mathbb{R}^d$  and that that minimizer is unique.

<sup>1</sup>Not to be confused with *strictly convex*, which is a weaker notion!

d) Consider the *damped Newton method*

$$x_{k+1} = x_k + \alpha_k p_k \quad \text{with} \quad p_k = -\nabla^2 f(x_k)^{-1} \nabla f(x_k),$$

where the step length parameter  $\alpha_k$  is chosen according to backtracking Armijo line search with parameters  $\hat{\alpha} > 0$ ,  $0 < c_1 < 1$ , and  $0 < \rho < 1$ .

Show that  $p_k$  is a descent direction in each step, and that the sequence  $x_k$  converges to the unique minimizer  $x^*$  of  $f$ .

*Hint: Use Theorem 1 in the note “Convergence of descent methods with backtracking (Armijo) linesearch...” by Anton Evgrafov.*

3] Consider the function

$$f(x, y) = 2x^2 + y^2 - 2xy + 2x^3 + x^4.$$

- a) Compute all stationary points of  $f$  and find all global or local minimisers of  $f$ .
- b) Consider the gradient descent method with backtracking for the minimisation of  $f$ . Use the parameters  $\rho = 1/2$  and  $c_1 = 1/4$ . Perform one step with starting value  $(x_0, y_0) = (-1, 0)$ . Does the method converge to a minimiser of  $f$ ?
- c) Consider Newton’s method with backtracking for the minimisation of  $f$ . Use the parameters  $\rho = 1/2$  and  $c_1 = 1/4$ . Perform one step with starting value  $(x_0, y_0) = (-1, 0)$ . Does the method converge to a minimiser of  $f$ ?

4] Let

$$A := \begin{pmatrix} 2 & -1 & -1 \\ -1 & 3 & -1 \\ -1 & -1 & 2 \end{pmatrix} \quad \text{and} \quad b := \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}.$$

Use the CG-method with initialisation  $x_0 = 0$  for solving the linear system  $Ax = b$ .

5] (Cf. Exercise 5.1 in Nocedal & Wright)

Implement the CG method for the solution of linear systems  $Ax = b$  with symmetric and positive definite matrix  $A \in \mathbb{R}^{n \times n}$ .

Use your method in the case where  $A$  is the Hilbert matrix, the elements of which are

$$A_{i,j} = \frac{1}{i+j-1}, \quad 1 \leq i, j \leq n.$$

Use the right hand side  $b = (1, 1, \dots, 1)^T$  and the initialisation  $x_0 = 0$ . Test your code for dimensions  $n = 5, 8, 12, 20$ . How many iterations are required to reduce the residual below  $10^{-6}$ ? Why do your results not contradict the theoretical results concerning the CG method that were discussed in the lecture?

*Hint: You might want to have a look at the condition number of the Hilbert matrix.*

(Note that in MATLAB the Hilbert matrix can be produced with the command `hilb`, and in Python using `scipy.linalg.hilbert`.)