



- 1 Constructively, a logarithmic barrier approach may be written as

$$\min_{x,y,s} x + y - \mu \log s \quad \text{subject to} \quad 1 - x^2 - y^2 - s = 0,$$

where $s (\geq 0)$ is the slack variable, and $\mu > 0$ is the barrier parameter which we intend to drive to 0. Introducing a Lagrange multiplier λ , the KKT conditions for this problem are

$$1 + 2x\lambda = 0, \quad 1 + 2y\lambda = 0, \quad -\frac{\mu}{s} + \lambda = 0, \quad \text{and} \quad 1 - x^2 - y^2 - s = 0.$$

This gives first that

$$\lambda = \frac{\mu}{s} \quad \text{and} \quad x = y = -\frac{s}{2\mu},$$

and inserted into the constraint equation, we find that

$$1 - \frac{s^2}{2\mu^2} - s = 0.$$

The relevant solution of this quadratic equation is $s = \mu(\sqrt{\mu^2 + 2} - \mu)$, and we end up with

$$x = y = -\frac{1}{2}(\sqrt{\mu^2 + 2} - \mu) \quad \text{and} \quad \lambda = (\sqrt{\mu^2 + 2} - \mu)^{-1}.$$

Since the Hessian of the Lagrangian to this problem is positive definite (check it!), the found KKT point is the unique global minimiser of the logarithmic barrier formulation. Notably, as $\mu \rightarrow 0^+$, we recover the exact solution $x^* = y^* = -1/\sqrt{2}$, with $\lambda^* = 1/\sqrt{2}$, of the original problem.

- 2 a) In matrix form—since we have m constraints—the augmented Lagrangian equals

$$\mathcal{L}_A(x, \lambda; \mu) = \frac{1}{2}\|x\|^2 - \lambda^\top(Ax - b) + \frac{\mu}{2}\|Ax - b\|^2,$$

where $\lambda \in \mathbb{R}^m$ is the Lagrange multiplier, and $\mu > 0$ is the penalty parameter. Trying to minimise \mathcal{L}_A with respect to x , we first note that $\mathcal{L}_A(\cdot, \lambda; \mu)$ is both smooth and coercive, where the latter property follows from the dominating $\frac{1}{2}\|x\|^2$ term (how?). Hence, a global minimiser exists. This point is also a stationary point, and computing

$$0 = \nabla_x \mathcal{L}_A(x, \lambda; \mu) = x - A^\top \lambda + \mu A^\top (Ax - b)$$

shows that the unique global minimiser, for all λ and all μ , is

$$\begin{aligned} x_{\lambda,\mu} &= \left(\frac{1}{\mu}\text{Id} + A^\top A\right)^{-1} A^\top \left(\frac{1}{\mu}\lambda + b\right) \\ &= A^\top \left(\frac{1}{\mu}\text{Id} + AA^\top\right)^{-1} \left(\frac{1}{\mu}\lambda + b\right). \end{aligned}$$

(Last transition was shown in exercise 3 b) in exercise set 7.)

- b) Since the exact solution and optimal Lagrange multiplier of the original optimisation problem equal

$$x^* = (A^\top A)^{-1} A^\top b = A^\top (AA^\top)^{-1} b = A^\top \lambda^* \quad \text{and} \quad \lambda^* = (AA^\top)^{-1} b,$$

we demand that $x_{\lambda,\mu} = x^*$ and see what happens: left-multiplying both sides by $(AA^\top)^{-1} A$ gives

$$\left(\frac{1}{\mu}\text{Id} + AA^\top\right)^{-1} \left(\frac{1}{\mu}\lambda + b\right) = \lambda^*,$$

or,

$$\frac{1}{\mu}\lambda + b = \left(\frac{1}{\mu}\text{Id} + AA^\top\right) \lambda^* = \frac{1}{\mu}\lambda^* + b.$$

In conclusion, the minimiser of the augmented Lagrangian equals that of the exact solution if and only if $\lambda = \lambda^*$, with no restrictions on $\mu > 0$.

- c) Before we should make any use of the iterative algorithm, it is vital to establish its *consistency* with the original optimisation problem which it intends to solve. By this we mean that the algorithm should solve the original problem in the limit: if $x^k \rightarrow x$ and $\lambda^k \rightarrow \lambda$, then $x = x^*$ and $\lambda = \lambda^*$.

As x^{k+1} is the minimum of $\mathcal{L}_A(\cdot, \lambda^k; \mu)$, we know that $x^{k+1} = x_{\lambda^k, \mu}$, and so inserting this into the iteration for the Lagrange multiplier yields that

$$\lambda^{k+1} = \lambda^k - \mu (Ax^{k+1} - b) = M(\lambda^k + \mu b),$$

where

$$\begin{aligned} M &= \text{Id} - AA^\top \left(\frac{1}{\mu}\text{Id} + AA^\top\right)^{-1} \\ &= \left[\left(\frac{1}{\mu}\text{Id} + AA^\top\right) - AA^\top \right] \left(\frac{1}{\mu}\text{Id} + AA^\top\right)^{-1} \\ &= \frac{1}{\mu} \left(\frac{1}{\mu}\text{Id} + AA^\top\right)^{-1} \\ &= (\text{Id} + \mu AA^\top)^{-1}. \end{aligned}$$

Suppose now that $x^k \rightarrow x$ and $\lambda^k \rightarrow \lambda$. Then from the Lagrange multiplier iteration we get

$$\lambda = M(\lambda + \mu b),$$

which implies that

$$(\text{Id} + \mu AA^\top) \lambda = \lambda + \mu b.$$

In other words,

$$\lambda = (AA^\top)^{-1}b = \lambda^*,$$

and therefore $x = x^*$ as well, because x^* is the minimiser of $\mathcal{L}_A(\cdot, \lambda^*; \mu)$ from question b). Thus the scheme is consistent.

Recall now from numerical linear algebra that the consistent Lagrange multiplier iteration will converge for all initial values if and only if $\rho(M) < 1$, where $\rho(M)$ denotes the spectral radius of M , that is, the largest eigenvalue of M in absolute value. Since A has full rank, matrix AA^\top is positive definite, with strictly positive eigenvalues. As such, the eigenvalues of

$$M^{-1} = \text{Id} + \mu AA^\top$$

are always strictly greater than 1, which means that $\rho(M) < 1$, as desired.