



Below follows *one* possible solution to the exercise set.

- 1] Let  $X$  be a vector space of dimension  $n$ , and  $\mathcal{L}(X)$  be the spaces of linear mappings on  $X$ . We want to show that  $\mathcal{L}(X)$  is isomorphic to  $\mathcal{M}_n$ , the space of  $n \times n$  matrices. Let  $\mathcal{B} = \{e_j\}_{j=1}^n$  be a basis on  $X$ . From here we can define a linear map  $\varphi : X \rightarrow \mathbb{F}^n$  by

$$\varphi \left( \sum_{i=1}^n \alpha_i e_i \right) = \begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_n \end{pmatrix}.$$

In particular,  $\varphi$  maps the basis of  $X$  to the standard basis on  $\mathbb{F}^n$ . The linearity of  $\varphi$  follows from the linearity of vector addition on  $\mathbb{F}^n$ . Note that  $\varphi$  is an isomorphism from  $X$  to  $\mathbb{F}^n$ . To see this, note that if  $\varphi(x) = \varphi(y)$ , where

$$x = \sum_{i=1}^n x_i e_i, \quad y = \sum_{i=1}^n y_i e_i.$$

Then  $x_i = y_i$  for all  $i$ , and thus  $x = y$ , and  $\varphi$  is injective. Moreover, for each  $\xi \in \mathbb{F}^n$ , where

$$\xi = \begin{pmatrix} \xi_1 \\ \vdots \\ \xi_n \end{pmatrix},$$

we can define the vector  $v \in X$  given by

$$v = \sum_{i=1}^n \xi_i e_i.$$

Then  $\varphi(v) = \xi$ , and so  $\varphi$  is also surjective. This shows that  $\varphi$  is an isomorphism, and moreover it has a well-defined inverse given by

$$\varphi \begin{pmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{pmatrix} = \sum_{i=1}^n \alpha_i e_i.$$

Note that any linear transformation on  $X$  is uniquely determined by how it acts on the basis vectors. Namely, for any  $T \in \mathcal{L}(X)$ , and any  $x \in X$ , we have

$$T(x) = T \left( \sum_{i=1}^n \alpha_i e_i \right) = \sum_{i=1}^n \alpha_i T(e_i).$$

We therefore define the map from  $\Phi : \mathcal{L}(X) \rightarrow \mathcal{M}_n$  given by

$$T \mapsto \Phi(T) = M_T = (\varphi(T(e_1)) \quad \dots \quad \varphi(T(e_n))).$$

That is, the  $j$  column of the matrix  $M_T$  is given by the vector  $T(e_j)$ .

We claim that this map is a bijection, and hence an isomorphism.

First of, for any matrix  $M \in \mathcal{M}_n$  we can define the linear transformation  $T_M$  by defining it on each of the basis vectors given by

$$T(e_j) = \varphi^{-1}(M_j),$$

where  $M_j$  is the  $j^{\text{th}}$  column of the matrix  $M$ . Then

$$\varphi(T_M) = (M_1 \quad \dots \quad M_n) = M,$$

which shows that the map  $\Phi$  is surjective. Moreover, assume that for some  $S, T \in \mathcal{L}(X)$  we have

$$\Phi(S) = \Phi(T).$$

Then we have

$$\varphi(S(e_j)) = \varphi(T(e_j)),$$

for each  $j$ . Since we showed that  $\varphi$  is injective it follows that  $S(e_j) = T(e_j)$ . Moreover, as  $S$  and  $T$  coincide on each basis vector they have to be the same. That is,  $S = T$  and so  $\Phi$  is injective. This shows that  $\Phi$  is an isomorphism.

**2** Let  $p_0 = 1$ , and define the polynomials  $p_j$  for  $1 \leq j \leq n$  by

$$p_j(x) = \prod_{i=1}^j (x - i + 1).$$

Moreover, define the map  $Dp(x) = p(x+1) - p(x)$

- a)** Find the matrix representation of  $D$  with respect to the basis  $\mathcal{B} = \{p_0, \dots, p_n\}$  and the basis  $\mathcal{M} = \{1, x, \dots, x^n\}$ .

Let us start with the basis  $\mathcal{M}$ . Note that  $D1 = 0$ . By the binomial formula, we know that for  $j > 1$

$$(x+1)^j = \sum_{i=0}^j \binom{j}{i} x^{j-i}.$$

From here we have

$$Dx^j = (x+1)^j - x^j = (x+1)^j = \sum_{i=1}^j \binom{j}{i} x^{j-i} = \sum_{i=0}^{j-1} \binom{j}{j-i} x^i.$$

Thus the matrix components of  $[D]_{\mathcal{M}}$  is given by

$$D_{ij} = \begin{cases} \binom{j-1}{j-i} & j > i, \\ 0 & j \leq i. \end{cases}$$

For  $n = 3$ , the matrix looks like

$$[D]_{\mathcal{M}} = \begin{pmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 2 & 3 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

For the basis  $\mathcal{B}$  we first note a few nice properties. Firstly, note that

$$p_j(x) = (x - j + 1)p_{j-1}(x).$$

Secondly, we note that

$$\begin{aligned} p_j(x+1) &= \prod_{i=1}^j ((x+1) - i + 1) = \prod_{i=1}^j (x - (j-1) + 1) \\ &= (x+1) \prod_{i=1}^{j-1} (x - j + 1) \\ &= (x+1)p_{j-1}(x). \end{aligned}$$

Thus, the difference operator  $D$  is given by

$$Dp_j(x) = p_j(x+1) - p_j(x) = (x+1)p_{j-1}(x) - (x-j+1)p_{j-1}(x) = jp_{j-1}(x),$$

for  $j \geq 1$ . We still have  $D1 = 0$ . This gives the matrix components

$$[D_{ij}]_{\mathcal{B}} = \begin{cases} j-1 & i = j-1 \\ 0, & \text{else.} \end{cases}$$

For  $n = 3$ , the matrix looks like

$$[D]_{\mathcal{B}} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

- b) It was shown in a) that  $Dp_j(x) = jp_{j-1}(x)$ .
- c) It is enough to consider the action on the basis elements as  $D$  is a linear transformation. You should convince yourself about this fact. We choose to work with the basis  $\mathcal{B}$ .

Since we have  $Dp_j(x) = jp_{j-1}(x)$ , it follows that for  $1 \leq i \leq j$

$$D^i p_j(x) = \frac{j!}{(j-i)!} p_{j-i}(x).$$

In particular,  $D^j p_j(x) = j! p_0(x) = j!$ , and so  $D^{j+1} p_j(x) = 0$  for any  $1 \leq j \leq n$ . but this means that for any  $p \in \mathcal{P}_n$ , we have

$$\begin{aligned} D^n p(x) &= D^n \left( \sum_{i=0}^n \alpha_i p_i(x) \right) = n! \alpha_n p_0(x) = n! \alpha_n, \\ D^{n+1} p(x) &= n! \alpha_n D p_0(x) = 0. \end{aligned}$$

This proves the claim. Note that the way the problem is stated is not completely correct as there exists polynomials  $p \in \mathcal{P}_n$  such that  $D^n p(x) = 0$ . Namely all the polynomials of degree strictly less than  $n$ , that is  $\alpha_n = 0$ . However,  $D^n$  does not vanish on  $\mathcal{P}_n$ , while  $D^{n+1}$  does.

For  $n = 3$  we have.

$$[D]_{\mathcal{B}} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad [D]_{\mathcal{B}}^2 = \begin{pmatrix} 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 6 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix},$$

$$[D]_{\mathcal{B}}^3 = \begin{pmatrix} 0 & 0 & 0 & 6 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad [D]_{\mathcal{B}}^4 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

3] Let consider the matrix

$$A = \begin{pmatrix} 15 & -6 & 2 \\ 35 & -14 & 5 \\ 7 & -3 & 2 \end{pmatrix}.$$

Find the eigenvalues and the generalized eigenspaces.

We start by finding the eigenvalues.

$$\det(A - \lambda I) = -\lambda^3 + 3\lambda^2 - 3\lambda + 1 = (1 - \lambda)^3.$$

The matrix has eigenvalues  $\lambda_i = 1$  for  $i \in \{1, 2, 3\}$ . From here we want to find the eigenvectors.

$$A - I = \begin{pmatrix} 14 & -6 & 2 \\ 35 & -15 & 5 \\ 7 & -3 & 1 \end{pmatrix} \sim \begin{pmatrix} 7 & -3 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

We can therefore conclude that the eigenvectors are given by

$$v_1 = \begin{pmatrix} 0 \\ 1 \\ 3 \end{pmatrix}, \quad v_2 = \begin{pmatrix} 1 \\ 0 \\ -7 \end{pmatrix}.$$

The generalized eigenspace is defined as

$$E_\lambda = \{v \in \mathbb{R}^3 : \text{There exists } m \in \mathbb{N} \text{ such that } (A - \lambda I)^m v = 0, (A - \lambda I)^{m-1} v \neq 0\}.$$

To find a generalized eigenvector, we want to see if we can find a vector  $z$  such that

$$(A - I)z \neq 0, \quad (A - I)^2 z = 0.$$

Note that  $(A - I)^2 = 0$ . In particular we can choose

$$z = v_1 \times v_2 = \begin{pmatrix} -7 \\ 3 \\ -1 \end{pmatrix}.$$

Then

$$(A - I)z = \begin{pmatrix} 14 & -6 & 2 \\ 35 & -15 & 5 \\ 7 & -3 & 1 \end{pmatrix} \begin{pmatrix} -7 \\ 3 \\ -1 \end{pmatrix} = \begin{pmatrix} -118 \\ -295 \\ -59 \end{pmatrix} \neq 0$$

while  $(A - I)^2 z = 0$ . We therefore have the generalized eigenspace for the eigenvalue  $\lambda = 1$  given by

$$E_1 = \text{span}\{v_1, v_2, z\} = \mathbb{R}^3.$$

**4** Let  $X$  be a finite dimensional vector space, and  $T : X \rightarrow X$  be a linear transformation. Prove that

$$X \supseteq \text{im}(T) \supseteq \text{im}(T^2) \supseteq \dots,$$

and that there exist an integer  $k$  such that  $\text{im}(T^k) = \text{im}(T^{k+1})$ .

Recall that the image is defined by

$$\text{im}(T) = \{x \in X : x = T(y) \text{ for some } y \in X\}.$$

We can prove the first part by a simple induction argument. The base case it follows from the definition of the image of  $T$ . That is  $\text{im}(T) \subseteq X$ .

Assume that we have  $X \supseteq \text{im}(T) \supseteq \dots \supseteq \text{im}(T^{j-1})$ . Then by definition of the image of  $T^j$  we know that if  $x \in \text{im}(T^j)$  then there exists some  $y \in X$  such that

$$x = T^j(y) = T^{j-1}(Ty) = T^{j-1}(z) \in \text{im}(T^{j-1}).$$

For the second part we note that the image of  $T^j$  is a subspace. This follows from the fact that  $T$  is a linear transformation. By the first part we have for each integer  $j$

$$\text{im}(T^{j-1}) \supseteq \text{im}(T^j).$$

In particular, this implies that  $\dim(\text{im}(T^j)) \leq \dim(\text{im}(T^{j-1}))$ .

Let  $n = \dim(X)$ . Then for every integer  $0 \leq k \leq n$  we have that either  $\dim(\text{im}(T^k)) = \dim(\text{im}(T^{k-1}))$  or  $\dim(\text{im}(T^k)) < \dim(\text{im}(T^{k-1}))$ . Consider first the case that for some integer  $k$  we have  $\dim(\text{im}(T^k)) = \dim(\text{im}(T^{k-1})) = m$ . Then there exists  $m$  linear independent vectors  $v_1, \dots, v_m \in \text{im}(T^k)$  such that  $\text{span}\{v_1, \dots, v_m\} = \text{im}(T^k)$ . Moreover, by the first part  $\text{im}(T^k) \subseteq \text{im}(T^{k-1})$ , and so  $v_1, \dots, v_m$  are  $m$  linearly independent vectors in  $\text{im}(T^{k-1})$ . Since  $\dim(\text{im}(T^{k-1})) = m$ , it follows from lemma 1.6 in the notes,  $\{v_1, \dots, v_m\}$  is a basis for  $\text{im}(T^{k-1})$ . Thus for any  $x \in \text{im}(T^{k-1})$  we have

$$x = \sum_{i=1}^m \alpha_i v_i \in \text{span}\{v_1, \dots, v_m\} = \text{im}(T^k).$$

This shows that  $\text{im}(T^{k-1}) \subseteq \text{im}(T^k)$ , and thus we have equality.

Assume on the other hand that  $\dim(\text{im}(T^k)) < \dim(\text{im}(T^{k-1}))$ . Since  $X$  is finite dimensional, there exists an integer  $k \leq n$  such that  $\dim(\text{im}(T^k)) = 0$ . Otherwise we would have had an equality of the dimensions. Since  $\text{im}(T^k)$  is a vector space, and the only zero dimensional vector space is  $\{0\}$ , it follows that  $\text{im}(T^k) = \{0\}$ . However, as  $T$  is a linear transformation, we know that  $T(0) = 0$ . Thus, for any  $x \in \text{im}(T^{k+1})$

$$x = T^{k+1}(z) = T(T^k(z)) = T(0) = 0.$$

This shows that

$$\text{im}(T^{k+1}) = \{0\} = \text{im}(T^k).$$