



Note that there are several ways to approach the problems, but that only one is presented here. Other solutions may be just as valid!

- 1 a) This linear system is much simpler to solve than a general one, due to all the structure in the coefficients. Observe that

$$(1) + (3) : \quad 2a_1 \quad + 2a_3 \quad = f_1 \quad + f_3 \quad (5)$$

$$(1) - (3) : \quad \quad 2a_2 \quad + 2a_4 = f_1 \quad - f_3 \quad (6)$$

$$(2) + (4) : \quad 2a_1 \quad - 2a_3 \quad = \quad f_2 \quad + f_4 \quad (7)$$

$$(2) - (4) : \quad \quad 2ia_2 \quad - 2ia_4 = \quad f_2 \quad - f_4. \quad (8)$$

Repeating a similar procedure again, we find

$$(5) + (7) : \quad 4a_1 \quad \quad \quad = f_1 + f_2 + f_3 + f_4$$

$$(5) - (7) : \quad \quad \quad 4a_3 \quad = f_1 - f_2 + f_3 - f_4$$

$$(6) - i(8) : \quad \quad 4a_2 \quad \quad \quad = f_1 - if_2 - f_3 + if_4$$

$$(6) + i(8) : \quad \quad \quad \quad \quad 4a_4 = f_1 + if_2 - f_3 - if_4,$$

where it only remains to divide by 4.

- b) The matrix B is given by

$$B = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & i & -1 & -i \\ 1 & -1 & 1 & -1 \\ 1 & -i & -1 & i, \end{bmatrix}$$

and from a) we read that

$$B^{-1} = \frac{1}{4} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -i & -1 & i \\ 1 & -1 & 1 & -1 \\ 1 & i & -1 & -i, \end{bmatrix}$$

which is equal to $\frac{1}{4}\overline{B} = \frac{1}{4}B^*$.

- 2 a) From the first question we know that $F_4 = B/2$ is unitary, which means that $F_4^*F_4 = I$, where I is the identity matrix. But this shows that the columns of

F_4 are orthonormal in \mathbb{C}^4 , because we also have

$$F_4^* F_4 = \begin{bmatrix} u_1^* \\ u_2^* \\ u_3^* \\ u_4^* \end{bmatrix} \begin{bmatrix} u_1 & u_2 & u_3 & u_4 \end{bmatrix} = \begin{bmatrix} \langle u_1, u_1 \rangle & \langle u_2, u_1 \rangle & \langle u_3, u_1 \rangle & \langle u_4, u_1 \rangle \\ \langle u_1, u_2 \rangle & \langle u_2, u_2 \rangle & \langle u_3, u_2 \rangle & \langle u_4, u_2 \rangle \\ \langle u_1, u_3 \rangle & \langle u_2, u_3 \rangle & \langle u_3, u_3 \rangle & \langle u_4, u_3 \rangle \\ \langle u_1, u_4 \rangle & \langle u_2, u_4 \rangle & \langle u_3, u_4 \rangle & \langle u_4, u_4 \rangle \end{bmatrix}.$$

b) In order to simplify this, we make the observation that

$$F_4 = F_4^T = \begin{bmatrix} u_1^T \\ u_2^T \\ u_3^T \\ u_4^T \end{bmatrix} = \begin{bmatrix} u_1^* \\ u_4^* \\ u_3^* \\ u_2^* \end{bmatrix}. \quad (9)$$

We can now compute

$$\begin{aligned} F_4^2 &= \begin{bmatrix} u_1^* \\ u_4^* \\ u_3^* \\ u_2^* \end{bmatrix} \begin{bmatrix} u_1 & u_2 & u_3 & u_4 \end{bmatrix} = \begin{bmatrix} \langle u_1, u_1 \rangle & \langle u_4, u_1 \rangle & \langle u_3, u_1 \rangle & \langle u_2, u_1 \rangle \\ \langle u_1, u_2 \rangle & \langle u_4, u_2 \rangle & \langle u_3, u_2 \rangle & \langle u_2, u_2 \rangle \\ \langle u_1, u_3 \rangle & \langle u_4, u_3 \rangle & \langle u_3, u_3 \rangle & \langle u_2, u_3 \rangle \\ \langle u_1, u_4 \rangle & \langle u_4, u_4 \rangle & \langle u_3, u_4 \rangle & \langle u_2, u_4 \rangle \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}, \end{aligned}$$

which in turn can be used to compute F_4^3 . This matrix simply reorders the columns of another matrix if multiplied on the right. Namely,

$$\begin{aligned} F_4^3 &= F_4 F_4^2 = \begin{bmatrix} u_1 & u_2 & u_3 & u_4 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} \\ &= \begin{bmatrix} u_1 & u_4 & u_3 & u_2 \end{bmatrix} \\ &= F_4^*, \end{aligned}$$

where the last equality comes from the observation in (9). It finally follows that

$$F_4^4 = F_4 F_4^3 = F_4 F_4^* = I,$$

since F_4 is unitary.

3 Linear independence of the v_i means, by definition, that if

$$\sum_{i=1}^n \alpha_i v_i = 0$$

for scalars α_i , then all the α_i are zero. Stated in a different way, if the α_i are *not* all zero, then

$$\sum_{i=1}^n \alpha_i v_i \neq 0.$$

In particular, for any fixed i we can choose $\alpha_i = 1$ and $\alpha_j = 0$ for $j \neq i$ to obtain

$$v_j \neq 0.$$

Hence all the v_i are different from the zero vector.

- 4 Suppose that $m > n$ (we show the contrapositive). Since the v_i span X , we can find scalars α_{ij} such that

$$u_i = \sum_{j=1}^n \alpha_{ij} v_j$$

for $i = 1, \dots, m$. The matrix $A = (\alpha_{ij})$ has m rows and n columns, and since $m > n$ the rows of A (which lie in \mathbb{K}^n) must be linearly dependent. We can therefore find scalars β_i , not all zero, such that

$$\sum_{i=1}^m \beta_i \alpha_{ij} = 0$$

for $j = 1, \dots, n$. But then

$$\begin{aligned} \sum_{i=1}^m \beta_i u_i &= \sum_{i=1}^m \beta_i \sum_{j=1}^n \alpha_{ij} v_j \\ &= \sum_{j=1}^n \left(\sum_{i=1}^m \beta_i \alpha_{ij} \right) v_j \\ &= 0 \end{aligned}$$

shows that the u_i are linearly dependent. (Hence if the u_i are linearly independent, then $m \leq n$.)

- 5 Every vector space has a basis, so let v_1, \dots, v_n be a basis for V . Next, define the map $T: \mathbb{R}^n \rightarrow V$ by

$$Tx = \sum_{i=1}^n x_i v_i.$$

We need to verify that T is linear, injective and surjective. These properties together will imply that T is an isomorphism (of vector spaces), and therefore that V is isomorphic to \mathbb{R}^n . If $\alpha, \beta \in \mathbb{R}$ and $x, y \in \mathbb{R}^n$, we find

$$\begin{aligned} T(\alpha x + \beta y) &= \sum_{i=1}^n (\alpha x_i + \beta y_i) v_i \\ &= \alpha \sum_{i=1}^n x_i v_i + \beta \sum_{i=1}^n y_i v_i \\ &= \alpha Tx + \beta Ty, \end{aligned}$$

which shows that T is linear.

For surjectivity, let $u \in V$ be arbitrary. Since the v_i form a basis, there are scalars x_i such that

$$u = \sum_{i=1}^n x_i v_i.$$

The right hand side of this equation is simply Tx , so $Tx = u$ and T is surjective.

Finally, if

$$0 = Tx = \sum_{i=1}^n x_i v_i,$$

then all the x_i must be zero by linear independence of the v_i . Thus $x = 0$, and so T is injective. A linear map being injective is equivalent to it having a trivial kernel (why?).