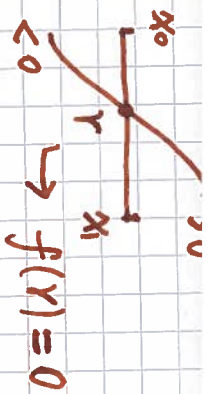


Recall ① solve  $f(x) = 0$

Bisection  
fixed point



$f(x) = 0 \Leftrightarrow x = g(x)$  : fixed point equation

$$x_{k+1} = g(x_k)$$

How to find optimal  $g$ ?

$g = x - \frac{f(x)}{f'(x)} \rightarrow$  Newton method

$$x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}$$

System of non-linear equations

$$\vec{f}(\vec{x}) = 0$$

$$f_1(x_1, \dots, x_n) = 0$$

$$f_n(x_1, \dots, x_n) = 0$$

We use Newton method (special fixed point method)

$$\vec{x}_{k+1} = \vec{x}_k - \underline{J}(\vec{x}_k)^{-1} \vec{f}(\vec{x}_k)$$

Jacobian matrix

$$\underline{J} = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \dots & \frac{\partial f_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_n}{\partial x_1} & \dots & \frac{\partial f_n}{\partial x_n} \end{pmatrix}$$

Example:

$$x_1^3 - x_2 + \frac{1}{4} = 0$$

$$x_1^2 + x_2^2 - 1 = 0$$

$$\vec{x}_0 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \vec{f}(\vec{x}_0) = \begin{pmatrix} \frac{1}{4} \\ 1 \end{pmatrix}$$

$$\vec{x}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} - \frac{\begin{pmatrix} 2 \\ 2 \end{pmatrix} \begin{pmatrix} 2 \\ 3 \end{pmatrix}}{8} \begin{pmatrix} \frac{1}{4} \\ 1 \end{pmatrix}$$

$$J = \begin{pmatrix} 3x_1^2 & -1 \\ 2x_1 & 2x_2 \end{pmatrix}$$

$$J^{-1} = \frac{1}{6x_1^2 x_2 + 2x_1} \begin{pmatrix} 2x_1 & 1 \\ -2x_1 & 3x_1^2 \end{pmatrix}$$

# ② ODE

Existence and uniqueness theorem for ODEs! (NOT Assumed)

$$\left. \begin{aligned} & y'(x) = f(x, y(x)) \\ & y(x_0) = y_0 \end{aligned} \right\}$$

Question: explain the examples.

Idea: (Picard)  $\int_{x_0}^x y'(x) dx$

(\*)



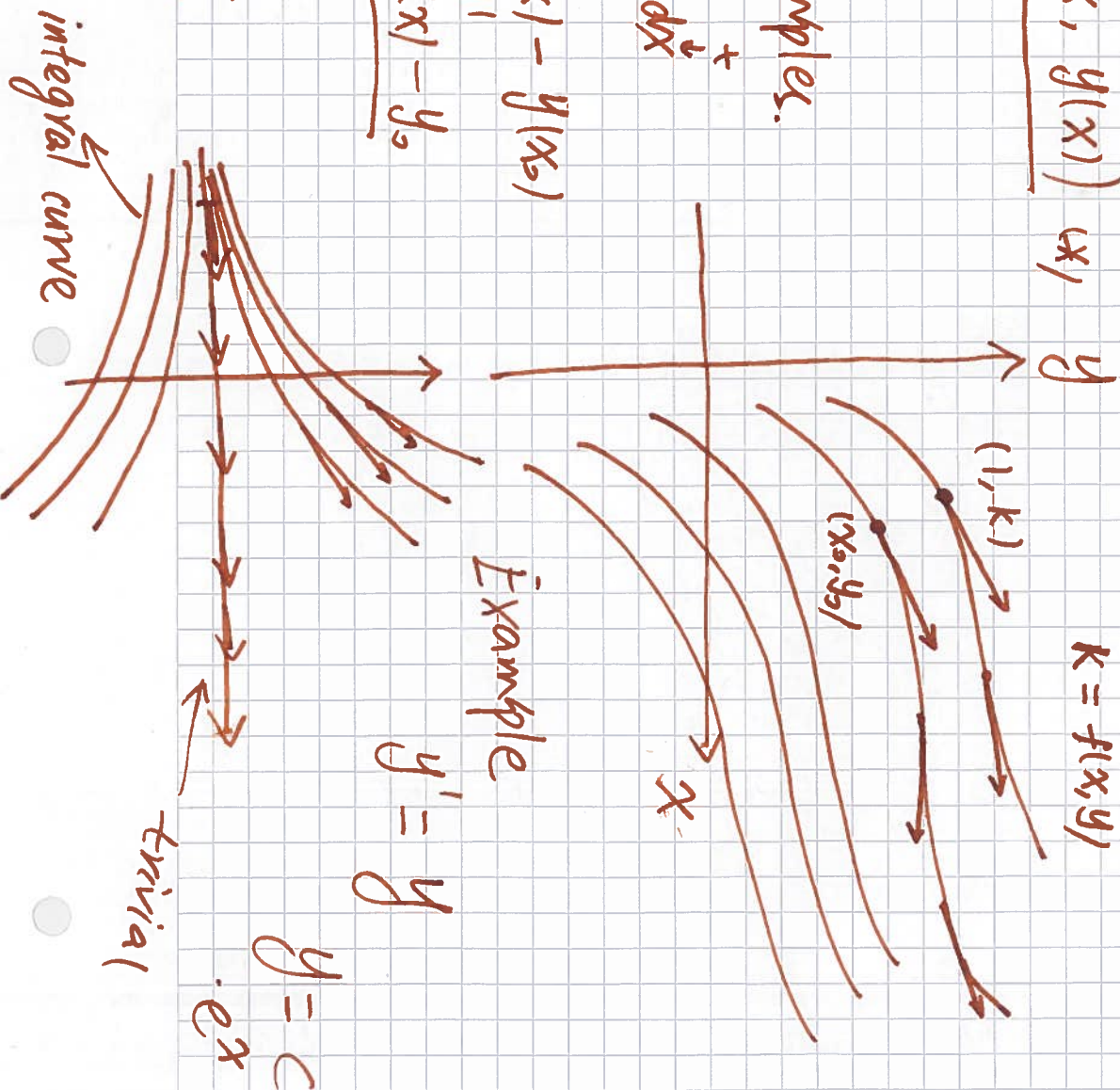
$$y(x) - y_0 = \int_{x_0}^x f(x, y(x)) dx \quad (**)$$

$$F(y)(x) = y_0 + \int_{x_0}^x f(x, y(x)) dx$$

(\*\*) :  $y = F(y)$

$$y(x) - y(x_0)$$

$$y(x) - y_0$$



Example:

$$y' = 1 + y^2$$

$$y(0) = 0$$

$$y = \tan x = \frac{\sin x}{\cos x}$$

Picard iteration:  $F(y) = 0 + \int_0^x 1 + y^2$

$$\varphi_0 \equiv y(0) = 0$$

$$\varphi_1 = F(\varphi_0) = \int_0^x 1 + 0^2 = x \quad (\varphi_1(t) = t)$$

$$\varphi_2 = F(\varphi_1) = \int_0^x 1 + t^2 dt = x + \frac{x^3}{3}$$

$$\varphi_3 = F(\varphi_2) = \int_0^x \left(1 + t + \frac{t^3}{3}\right)^2 dt$$

$$= \int_0^x \left(1 + t^2 + \frac{2}{3}t^4 + \frac{t^6}{9}\right) dt$$

$$= x + \frac{x^3}{3} + \frac{2}{15}x^5 + \frac{x^7}{63}$$

$\varphi_\infty$ : Taylor expansion of  $\tan x$ !

④

Picard iteration (fixed point iteration)

$$\varphi_0 \equiv y_0$$

$$\varphi_1 := F(\varphi_0)$$

⋮

$$\varphi_{k+1} := F(\varphi_k)$$

$$\varphi_{k+1}(x) = y_0 + \int_{x_0}^x f(t, \varphi_k(t)) dt$$

Estimate  $\varphi_{k+1} - \varphi_k$

$$\varphi_{k+1}(x) - \varphi_k(x) = \int_{x_0}^x \frac{f(t, \varphi_{k+1}) - f(t, \varphi_k)}{dt} dt$$

$$\textcircled{1} \quad |f(t, \varphi_k) - f(t, \varphi_{k+1})| \leq L |\varphi_k - \varphi_{k+1}|$$

Lipschitz condition.

$f: c!$  w.r.t.  $y \quad |L_{\max}| = \max |f_y|$

$$\textcircled{2} \Rightarrow | \varphi_{k+1}(x) - \varphi_k(x) | \leq L \int_{x_0}^x | \varphi_k(t) - \varphi_{k+1}(t) | dt$$

When  $|x - x_0| \cdot L < \frac{1}{2}$

$$\| \varphi_{k+1} - \varphi_k \|_{\infty} = \max | \varphi_{k+1} - \varphi_k | \leq \frac{1}{2} \| \varphi_k - \varphi_{k+1} \|$$

$$\| \varphi_{k+1} - \varphi_{k+1} \|_{\infty} \leq \frac{1}{2} \| \varphi_k - \varphi_{k+1} \| \quad (\text{Estimate})$$

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Estimate  $\Rightarrow$

$$\| \varphi_{k+n} - \varphi_k \| \leq \| \varphi_{k+n} - \varphi_{k+n-1} \| + \dots + \| \varphi_{k+1} - \varphi_k \|$$

$$\leq \| \varphi_{k+1} - \varphi_k \| \left( 1 + \frac{1}{2} + \left(\frac{1}{2}\right)^2 + \dots + \left(\frac{1}{2}\right)^{n-1} \right)$$

$$\leq 2 \| \varphi_{k+1} - \varphi_k \|$$

$$\leq 2^{-k+n} \| \varphi_1 - \varphi_0 \| \rightarrow 0 \quad (k \rightarrow \infty)$$

$\Downarrow$

$\{ \varphi_k(x) \}$  is a Cauchy sequence, for all

$$|x - x_0| < \frac{1}{2L}$$

$\Downarrow$

$$\lim_{k \rightarrow \infty} \varphi_k(x) := \varphi(x) \quad \Rightarrow \quad \exists \cdot \& \perp$$

Summary:

For  $|x - x_0| < \frac{1}{2L}$ , we have

$$\left. \begin{array}{l} y' = f(x, y) \\ y(x_0) = y_0 \end{array} \right\} \text{ a unique solution for } y(x) = y_0.$$

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# Numerical way:

$$\left. \begin{aligned}
 y' &= f(x, y) \\
 y(x_0) &= y_0
 \end{aligned} \right\} \begin{array}{l} \text{Picard} \\ \Leftrightarrow \\ y(x) = y_0 + \int_{x_0}^x f(t, y(t)) dt \end{array}$$

$$\text{Euler} = \frac{\int_{x_0}^x f(t, y(t)) dt}{\int_{x_0}^x 1 dt} \sim (x-x_0) \cdot f(x_0, y_0)$$

$$\text{Heun: } \int_{x_0}^x f(t, y(t)) dt \sim (x-x_0) \left( \frac{f(x_0, y_0) + f(x, y)}{2} \right)$$

## Classical Runge-Kutta:

$$\int_{x_0}^x f(t, y(t)) dt \sim (x-x_0) \cdot \frac{f(x_0, y_0) + 4f(\frac{1}{2}) + f(x, y)}{6}$$

middle point

$$\int_0^1 f \sim \frac{f(0) + 4f(\frac{1}{2}) + f(1)}{6}$$

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Euler:

$$y(x) \approx y_0 + (x-x_0) f(x_0, y_0)$$

Let

$$h = x - x_0 \Rightarrow$$

$$y(x_0+h) \approx$$

$$y_0 + h f(x_0, y_0)$$

Start from  $(x_0, y_0)$

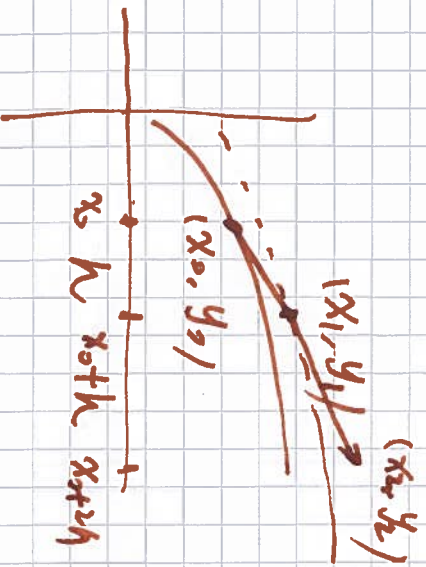
$$y_1 = y_0 + h f(x_0, y_0)$$

$$x_1 = x_0 + h$$

!

$$y_{k+1} = y_k + h f(x_k, y_k)$$

$$x_{k+1} = x_k + h$$



Example:

}  $y' = -100y$

c. e.  $-100x$

solution

$$y_{k+1} = y_k + h \cdot (-100) y_k = (1 - 100h) y_k$$

$$|1 - 100h| > 1 \Rightarrow |y_{k+1}| > |y_k|$$