

# TMA4130 MATEMATIKK 4N

Lecture 11: Unit Step Function (Heaviside Function). Second Shifting Theorem ( $t$ -Shifting). Dirac's Delta Function.

Elisabeth Köbis

September 27, 2021

# Unit Step Function (Heaviside Function) $u(t - a)$

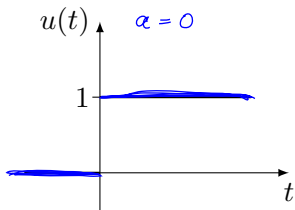
## Definition: Unit Step Function (Heaviside Function)

$$u(t - a)$$

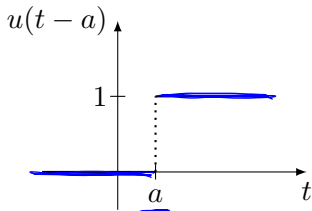
Let  $a \geq 0$ . The **unit step function** (or **Heaviside function**)

$u(t - a)$  is defined as follows:

$$u(t - a) := \begin{cases} 0 & (t < a) \\ 1 & (t > a) \end{cases} \quad \begin{matrix} \leq & < \\ > & \geq \end{matrix}$$

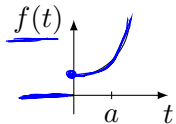


**Figure:** The unit step function  $u(t)$  for  $a = 0$  (with jump at 0).

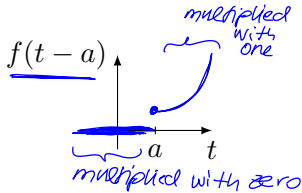


**Figure:** The unit step function  $u(t - a)$  (with jump at  $a$ ).

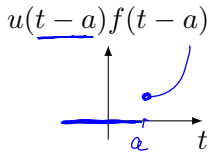
# Shifted Functions



**Figure:** Function  $f(t)$  with  $f(t) = 0$  for  $t < 0$ .



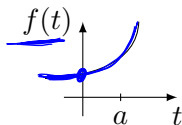
**Figure:** Function  $f(t-a)$ .



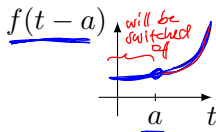
**Figure:** Function  $u(t-a)f(t-a)$ .

$$f(t-a) = f(a-a) = f(0) \quad \text{for } t=a$$

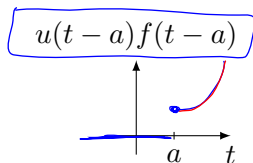
# Shifted and Switched On/Off-Functions



**Figure:** Function  $f(t)$ .



**Figure:** Function  $f(t - a)$ .



**Figure:** Function  $u(t - a)f(t - a)$ .

# Laplace Transform of the unit step function

$$\begin{aligned}\mathcal{L}\{u(t-a)\} &= \int_0^{\infty} e^{-st} u(t-a) dt \\ &= \int_a^{\infty} e^{-st} \cdot 1 dt \\ &= \left[ -\frac{1}{s} \cdot e^{-st} \right]_a^{\infty} \\ &= 0 - \left( -\frac{1}{s} \cdot e^{-s \cdot a} \right) \\ &= \underline{\underline{\frac{1}{s} \cdot e^{-sa}}}\end{aligned}$$

## Theorem: Second Shifting Theorem; Time Shifting

If  $\underline{f(t)}$  has the transform  $\underline{F(s)}$ , then the function

$$\underline{\tilde{f}(t)} = \underline{f(t-a)u(t-a)} := \begin{cases} 0 & (t < a) \\ \underline{f(t-a)} & (t > a) \end{cases}$$

has the transform  $\underline{e^{-as}F(s)}$ . That is, if  $\mathcal{L}(f) = F(s)$ , then

$$\mathcal{L}\{\underline{f(t-a)u(t-a)}\} = \underline{e^{-as}F(s)}.$$

Or, if we take the inverse on both sides, we can write

$$\underline{f(t-a)u(t-a)} = \underline{\mathcal{L}^{-1}\{e^{-as}F(s)\}}.$$

Proof:  $e^{-as} \cdot F(s) = e^{-as} \cdot \int_0^{\infty} e^{-st} \cdot f(t) dt$

$$= \int_0^{\infty} e^{-s(\tau+a)} f(\tau) d\tau$$

Substitution:  $t := \tau + a \Rightarrow \tau = t - a$ ,  $dt = d\tau$   
 $\tau = 0 \Rightarrow t = a$

$$\Rightarrow \underline{e^{-as} F(s)} = \int_a^{\infty} e^{-st} \cdot \underline{f(t-a)} dt$$

$$= \int_0^{\infty} e^{-st} \cdot \underbrace{u(t-a) \cdot f(t-a)}_{=: \tilde{f}(t)} dt$$

$$= \underline{\int_0^{\infty} e^{-st} \tilde{f}(t) dt}$$

## Example

Write the following function using unit step functions and find its transform.

$$f(t) = \begin{cases} 2 & (0 < t < 1) \\ \frac{1}{2}t^2 & (1 < t < \frac{1}{2}\pi) \\ \cos t & (t > \frac{1}{2}\pi). \end{cases}$$





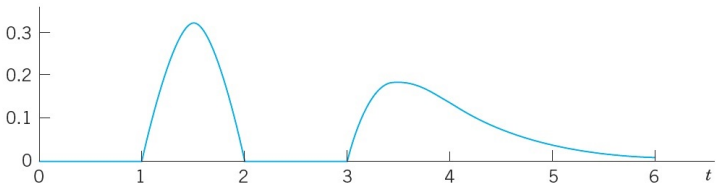




## Example

Find the inverse transform  $f(t)$  of

$$F(s) = \frac{e^{-s}}{s^2 + \pi^2} + \frac{e^{-2s}}{s^2 + \pi^2} + \frac{e^{-3s}}{(s + 2)^2}.$$



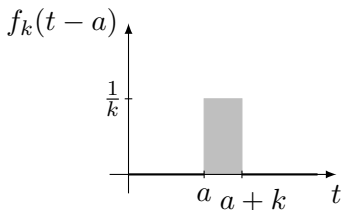
**Figure:**  $f(t) = \frac{1}{\pi} \sin(t(t-1))u(t-1) + \frac{1}{\pi} \sin(t(t-2))u(t-2).$

# Dirac's Delta Function

Consider the function

$$f_k(t - a) = \begin{cases} \frac{1}{k} & (a \leq t \leq a + k) \\ 0 & (\text{else}). \end{cases}$$

This function represents, for instance, a force of magnitude  $\frac{1}{k}$  acting from  $t = a$  to  $t = a + k$ , where  $k$  is positive and small. In mechanics, the integral of a force acting over a time interval  $a \leq t \leq a + k$  is called the **impulse** of the force.

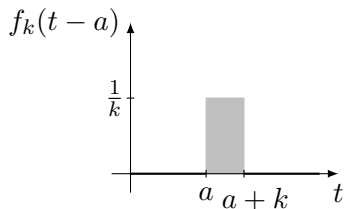


**Figure:** Function  $f_k(t - a)$ .

# Dirac's Delta Function

The impulse of  $f_k$  is

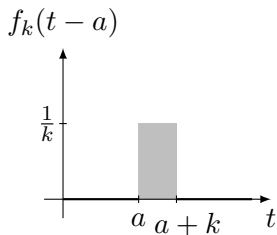
$$I_k := \int_0^{\infty} f_k(t - a) dt = \int_a^{a+k} \frac{1}{k} dt =$$



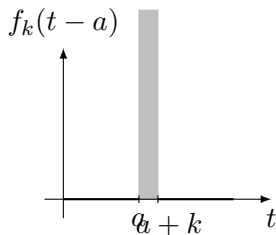
**Figure:** Function  $f_k(t - a)$ .

# Dirac's Delta Function

Consider  $k \rightarrow 0$ :



**Figure:** Function  $f_k(t-a)$ .



**Figure:** Function  $f_k(t-a)$ .



# Dirac's Delta Function

## Definition: Dirac's Delta Function (Unit Impulse Function) $\delta(t - a)$

Dirac's delta function is defined as

$$\delta(t - a) := \lim_{k \rightarrow 0} f_k(t - a) = \begin{cases} \infty & (t = a) \\ 0 & (\text{else}). \end{cases}$$

## Remark

Furthermore, we define  $\int_0^\infty \delta(t - a) dt = 1$ . However, from calculus we know that a function which is everywhere 0 except at a single point must have the integral equal to 0. Therefore,  $\delta(t - a)$  is not a function in the ordinary sense as used in calculus, but a so-called generalized function.

# Sifting Property of Dirac's Delta Function

Given a *continuous* function  $g(t)$ , it holds

$$\int_0^{\infty} g(t)\delta(t - a)dt = g(a).$$

# Laplace Transform of Dirac's Delta Function

## Example

Determine the response of the damped mass-spring system under a square wave, modeled by

$$y'' + 3y' + 2y = r(t) = u(t - 1) - u(t - 2), \quad y(0) = 0, \quad y'(0) = 0.$$





## Example

Find the response of the system in the previous example with the square wave replaced by a unit impulse at time  $t = 1$ , that is, determine the response of the damped mass-spring system, modeled by

$$y'' + 3y' + 2y = r(t) = \delta(t - 1), \quad y(0) = 0, \quad y'(0) = 0.$$









# References

The material of this lecture was based on Chapter 6.3 and 6.4 of the book

*Advanced Mathematical Engineering* by Erwin Kreyszig (John Wiley & Sons, 10th edition, 2011).

Moreover, we recommend the lecture notes by Morten Nome (in Norwegian), who taught the 2019 edition of this course. You can download Lecture 1 of Morten's lecture notes collection here:

<https://www.math.ntnu.no/emner/TMA4125/2019v/notater/01-laplacetransform.pdf>

# Next lecture

We continue with the Laplace transform by considering:

- ▶ Convolution
- ▶ Integral equations