

TMA4130 MATEMATIKK 4N

Lecture 10: Transforms of Derivatives and Integrals. ODEs

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Plan for the day

After today's lecture, you should be familiar with

- ▶ the Laplace transform of derivatives and integrals
- ▶ solving ODEs with the Laplace transform.

Solving linear ODEs and related initial value problems

The Laplace transform is a method of solving ODEs and initial value problems. The crucial idea is that operations of calculus on functions are replaced by operations of algebra on transforms. Roughly, differentiation of $f(t)$ will correspond to multiplication of $\mathcal{L}(f)$ by s and integration of $f(t)$ to division of $\mathcal{L}(f)$ by s . To solve ODEs, we must first consider the Laplace transform of derivatives.

Theorem: Laplace Transform of Derivatives

The transforms of the first and second derivatives of $f(t)$ satisfy

$$\mathcal{L}(f') = s\mathcal{L}(f) - f(0) \quad (1)$$

$$\mathcal{L}(f'') = s^2\mathcal{L}(f) - sf(0) - f'(0). \quad (2)$$

Formula (1) holds if $f(t)$ is continuous for all $t \geq 0$ and satisfies the growth restriction¹ and $f'(t)$ is piecewise continuous on every finite interval on the semi-axis $t \geq 0$. Similarly, (2) holds if f and f' are continuous for all $t \geq 0$ and satisfy the growth restriction and f'' is piecewise continuous on every finite interval on the semi-axis $t \geq 0$.

¹ $\exists M, k$ s.t. $\forall t \geq 0: |f(t)| \leq Me^{kt}$.

Theorem: Laplace Transform of the Derivative $f^{(n)}$ of Any Order

Let $f, f', \dots, f^{(n-1)}$ be continuous for all $t \geq 0$ and satisfy the growth restriction². Furthermore, let $f^{(n)}$ be piecewise continuous on every finite interval on the semi-axis $t \geq 0$. Then the transform of $f^{(n)}$ satisfies

$$\mathcal{L}(f^{(n)}) = s^n \mathcal{L}(f) - s^{n-1} f(0) - s^{n-2} f'(0) - \dots - f^{(n-1)}(0).$$

² $\exists M, k$ s.t. $\forall t \geq 0: |f^{(i)}(t)| \leq M e^{kt}$.

Example

Let $f(t) = t \sin \omega t$. Find $\mathcal{L}(f'')$ and $\mathcal{L}(f)$.

Example

Let $f(t) = \cos \omega t$ and $g(t) = \sin \omega t$. Find $\mathcal{L}(f)$ and $\mathcal{L}(g)$.

Theorem: Laplace Transform of Integral

Let $F(s)$ denote the transform of a function $f(t)$ which is piecewise continuous for $t \geq 0$ and satisfies a growth restriction³. Then, for $s > 0$ and $t > 0$,

$$\mathcal{L} \left\{ \int_0^t f(\tau) d\tau \right\} = \frac{1}{s} F(s), \text{ thus } \int_0^t f(\tau) d\tau = \mathcal{L}^{-1} \left\{ \frac{1}{s} F(s) \right\}.$$

³ $\exists M, k$ s.t. $\forall t \geq 0 : |f(t)| \leq M e^{kt}$.

Example

Find the inverse of $\frac{1}{s(s^2 + \omega^2)}$ and $\frac{1}{s^2(s^2 + \omega^2)}$.

Differential Equations, Initial Value Problems

Let us now discuss how the Laplace transform method solves ODEs and initial value problems. We consider an initial value problem

$$y'' + ay' + by = r(t), \quad y(0) = K_0, \quad y'(0) = K_1,$$

where a and b are constant.

$r(t) \dots$

$y(t) \dots$

In Laplace's method we perform three steps:

Step 1. Setting up the subsidiary equation.

Step 2. Solution of the subsidiary equation by algebra.

Step 3. Inversion of Y to obtain $y = \mathcal{L}^{-1}(Y)$.

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Example

Solve

$$y'' - y = t, \quad y(0) = 1, \quad y'(0) = 1.$$

Comparison with the Usual Method

Example

Solve

$$y'' + y' + 9y = 0, \quad y(0) = 0.16, \quad y'(0) = 0.$$

Advantages of the Laplace Method

1. Solving a nonhomogeneous ODE does not require first solving the homogeneous ODE.
2. Initial values are automatically taken care of.
3. Complicated inputs $r(t)$ (right sides of linear ODEs) can be handled very efficiently, as we show later.

Shifted Data Problems

Example

Solve

$$y'' + y = 2t, \quad y\left(\frac{1}{4}\pi\right) = \frac{1}{2}\pi, \quad y'\left(\frac{1}{4}\pi\right) = 2 - \sqrt{2}.$$

Conclusion

$$F(s) := \mathcal{L}(f) := \int_0^{\infty} e^{-st} f(t) dt$$

What we have learned today

- ▶ Laplace Transform of the derivative of a function
- ▶ Laplace Transform of the integral
- ▶ Solving ODEs and Initial Value Problems using Laplace Transform
- ▶ Shifted data problems

Next Lecture

Chapter 6.3, 6.4 in Kreyszig

- ▶ Unit Step Function (Heaviside Function)
- ▶ Second Shifting Theorem (t -Shifting)
- ▶ Dirac's Delta Function

References

The material of this lecture was based on Chapter 6.2 of the book

Advanced Mathematical Engineering by Erwin Kreyszig (John Wiley & Sons, 10th edition, 2011)

and Chapter 6 in

Differential Equations Demystified by Steven G. Krantz (McGraw-Hill, 2005).

Moreover, we recommend the lecture notes by Morten Nome (in Norwegian), who taught the 2019 edition of this course. You can download Lecture 1 of Morten's lecture notes collection here:

<https://www.math.ntnu.no/emner/TMA4125/2019v/notater/01-laplacetransform.pdf>