

Lecture XXIV

This time:

Last time:

solving boundary value problems

① The phenomenon of stiffness.

$$\begin{aligned} \text{Tol}_1 &= Dh_1^{p+1} \\ \text{Tol}_2 &= Dh_2^{p+1} \end{aligned} \quad \rightarrow \quad \frac{h_1}{h_2} = \left(\frac{\text{Tol}_1}{\text{Tol}_2} \right)^{\frac{1}{p+1}}$$

focusing on linear systems as 1st order approx to a general nonlinear system, using the toy equation

$$\dot{y} = \lambda y, \quad \lambda < 0$$

Euler stepping: $y_{n+1} = (1 + \lambda h) y_n$

$$\rightarrow \text{stability} \iff -1 < 1 + \lambda h < 1$$

corrected \rightarrow $-2 < \lambda h < 0$

when $\lambda \gg 1$, h must satisfy a more restrictive constraint than ~~given~~ prescribed by tolerance.

stability function $R(z)$

$$y_{n+1} = R(z) y_n, \quad z = \lambda h$$

$R(z)$ is a polynomial for multistep methods.

Dahlquist's theorem (1963) implied that explicit methods always has a stability function that is unbounded over $\lambda < 0$. — can never be $A(0)$ -stable.

we should like for $\lambda < 0$ to be sufficient a ~~condition~~ ^{condition} & the numerical method not to impose further constraints on h that competes with the one imposed by Tol. this is $A(0)$ -stability.

Consider Butcher tableaux:

$$\begin{array}{c|c} 1 & 1 \\ \hline 1 & 1 \end{array}$$

backward / implicit Euler's method

$$\begin{array}{c|cc} 0 & 0 & 0 \\ 1 & \frac{1}{2} & \frac{1}{2} \\ \hline 1 & \frac{1}{2} & \frac{1}{2} \end{array}$$

trapezoidal rule

$$y_{n+1} = hf(x_{n+1}, y_{n+1}) + y_n$$

$$y_{n+1} = h \underline{\underline{\Lambda}} y_{n+1} + g(x_{n+1}) + y_n \quad \underline{\underline{\Lambda}} \leq 0$$

$$(\underline{\underline{1}} - h \underline{\underline{\Lambda}}) y_{n+1} = g(x_{n+1}) + y_n$$

Λ is always invertible.

② Numerical Differentiation

three elements methods.

$$f'(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$

$$= \lim_{h \rightarrow 0} \frac{f(x) - f(x-h)}{h}$$

$$= \lim_{h \rightarrow 0} \frac{f(x+h) - f(x-h)}{2h}$$

when $f \in C^1$

define to take the limit:

$$D_h f(x) = \frac{f(x+h) - f(x)}{h} \quad (\text{forward})$$

$$\frac{f(x) - f(x-h)}{h} \quad (\text{backwards})$$

$$\delta_{2h} f(x) = \frac{f(x+h) - f(x-h)}{2h} \quad (\text{central})$$

$$\text{or } \delta_h f(x) = \frac{f(x+\frac{h}{2}) - f(x-\frac{h}{2})}{h}$$

on arbitrary grid of size $\frac{h}{2}$.

second derivatives:

$$D_h^2 f(x) = \frac{f(x+2h) - 2f(x+h) + f(x)}{h^2}$$

$$\delta_h^2 f(x) = \frac{f(x+h) - 2f(x) + f(x-h)}{h^2}$$

Thm Let $f \in C^4([x-h, x+h])$. Then,

$$\exists \xi \in [x-h, x+h] :$$

$$e_D^1(x; h) := f'(x) - D_h f(x) = -\frac{1}{2} f''(\xi) h$$

$$\exists \eta \in [x-h, x+h] :$$

$$e_D^2(x; h) := f'(x) - \delta_h f(x) = -\frac{1}{6} f^{(3)}(\eta) h^2$$

$$\exists \xi \in [x-h, x+h] :$$

$$e_D^2(x; h) := f''(x) - \delta_h^2 f(x) = -\frac{1}{12} f^{(4)}(\xi) h^2$$

corrected
↓
2

Pf. By Taylor's Expansion.

XXV, 1 Two Point Boundary Value Problems

Consider the 2nd order linear ODE:

$$u'' + p(x) u' + q(x) u = r(x)$$

$$x \in [a, b], \quad u(a) = u_a, \quad u(b) = u_b$$

Apply FEM directly:

discretization of space:

i) $x_n = a + nh$, $h = \frac{b-a}{N}$, $n = 0, 1, \dots, N$

ii) At each grid pt. x_n , replace the derivatives:

$$r(x_n) = \frac{u(x_n+h) - 2u(x_n) + u(x_n-h)}{h^2}$$

$$+ p(x_n) \frac{u(x_n+h) - u(x_n-h)}{2h}$$

$$+ q(x_n) u(x_n) + O(h^2)$$

iii) Replacing $u(x_n)$ by U_n :

$$\frac{1}{h^2} (U_{n+1} - 2U_n + U_{n-1})$$

$$+ \frac{p(x_n)}{2} h (U_{n+1} - U_{n-1}) + q(x_n) U_n h^2$$

$$iv) \underline{U} = (U_0, \dots, U_N)^T$$

$$\underline{A} \underline{U} = \underline{b} \quad \leftarrow \text{depends on } r(x_n), h$$

↑ unknown to be solved.

↑ depends on $p(x_n), q(x_n), h$

$$\underline{A} = \begin{pmatrix} 1 & 0 & & & \\ v_1 & d_1 & w_1 & & \\ & v_2 & d_2 & w_2 & \\ & & \ddots & \ddots & \\ & & & v_{N-1} & d_{N-1} & w_{N-1} \\ & & & & & 0 & 1 \end{pmatrix}$$

$$\underline{A} = \begin{pmatrix} 1 & 0 & & & \\ \hline v_1 & d_1 & w_1 & & \\ v_2 & d_2 & w_2 & & \\ & \ddots & \ddots & \ddots & \\ v_{N-1} & d_{N-1} & w_{N-1} & & \\ \hline & & & 0 & \dots & 1 \end{pmatrix}$$

$$\left. \begin{aligned} v_i &= 1 - \frac{h}{2} p(x_i) \\ d_i &= -2 + h^2 q(x_i) \\ w_i &= 1 + \frac{h}{2} p(x_i) \end{aligned} \right\} \text{ for } i = 1, \dots, N-1$$

$$v_N = 0, \quad d_0 = d_N = 1, \quad w_0 = 0$$

$$(\underline{A})_{ij} = w_i \delta_{i, j-1} + d_i \delta_{ij} + v_i \delta_{i, j+1}$$

Kronecker delta : $\delta_{ij} = \begin{cases} 1 & i=j \\ 0 & \text{else} \end{cases} \quad j = 1, \dots, N-1$

$$\underline{b} = (u_a, h^2 r(x_1), \dots, h^2 r(x_{N-1}), u_b)^T$$

$$\underline{A} \underline{U} = \underline{b}$$

iv) invert \underline{A} to solve for \underline{U} :

$$\underline{U} = \underline{A}^{-1} \underline{b}$$

Example XXIV.1

Consider

$$u'' + 2u' - 3u = 9x$$

$$u(0) = u_c = 1$$

$$u(1) = u_b = e^{-3} + 2e^{-5}$$

$$\approx 0.48635$$

$$u(x) = e^{-3x} + 2e^x - 3x - 2$$

$$h^2 9x_n = \frac{U_{n+1} - 2U_n + U_{n-1}}{h^2} + 2h \frac{U_{n+1} - U_{n-1}}{2h} - 3U_n h^2$$

$$U_0 = 1, \quad U_N = 0.48635 \quad \leftarrow \text{fixed.}$$

Suppose now we specify the gradient at the boundary:

$$u'' + p(x)u' + q(x)u = r(x) \quad x \in [a, b]$$

$$u'(a) = u'_a, \quad u(b) = u_b$$

how shall we discretize the gradient BV?

suggestion 1: $u'_a = \frac{u(x_1) - u(x_0)}{h} + O(h)$

so $u'_a = \frac{U_1 - U_0}{h}$

suggestion 2: non-physical / false grid:

assume there is a pt. x_{-1} to the left of x_0 ,

i.e. $x_{-1} = a - h$.

assume an approx. value U_{-1} at x_{-1} , and write

$$u'_a = \frac{U_1 - U_{-1}}{2h}$$

so $U_{-1} = U_1 - 2h u'_a$

the false grid pt assumption changes our U'' eq:

$$r(x_0) = \frac{U_1 - 2U_0 + U_{-1}}{h^2} + p(x_0) \frac{U_1 - U_{-1}}{2h} + q(x_0) U_0$$

inserting $U_{-1} = U_1 - 2h u_a'$, the eq is:

$$r(x_0) = \frac{2U_1 - 2U_0 - 2h u_a'}{h^2} + p(x_0) u_a' + q(x_0) U_0$$

$$2U_1 + (-2 + q(x_0)h^2)U_0 = h^2 r(x_0) - p(x_0)u_a'h^2 + 2u_a'h$$

Example XXIV.2

same equation: $u'' + 2u' - 3u = 9x$

$$u'(0) = u_a' = -4$$

$$u(1) = u_b = 0.48635$$

with $h = 0.25$

$$\underline{A} = \begin{pmatrix} -2.1875 & 2 & & & \\ 0.75 & -2.1875 & 1.25 & & \\ & & & \ddots & \\ & & & & 0 & 1 \end{pmatrix}$$