



Norwegian University of  
Science and Technology

Department of Mathematical Sciences

## Examination paper for **TMA4130 Matematikk 4N**

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**Examination time (from–to):** 09:00–13:00

**Permitted examination support material:** Kode C:

Bestemt, enkel kalkulator

Rottmann: Matematisk formelsamling

### Other information:

- All answers have to be justified, and they should include enough details in order to see how they have been obtained.
- All sub-problems carry the same weight for grading.
- Good Luck!

**Language:** English

**Number of pages:** 3

**Number of pages enclosed:** 2

**Checked by:**

Informasjon om trykking av eksamensoppgave

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**Problem 1** Let  $f(x)$  be defined as

$$f(x) = \frac{\pi}{4} - \frac{x}{2}, \quad \text{where } 0 < x < \pi.$$

a) Find the Fourier cosine series of  $f(x)$ .

b) Use the result to compute the value of the series  $\sum_{n=0}^{\infty} \frac{1}{(2n+1)^2}$ .

**Problem 2** Solve the integral equation

$$\int_{-\infty}^{\infty} f(x-t)e^{-|t|} dt = e^{-\frac{x^2}{2}}$$

using Fourier transforms. (**Hint:** You may need the formula for the Fourier transform of derivatives.)

**Problem 3** Consider the ordinary differential equation

$$\begin{aligned} y'' - 3y' + 2y &= r, \\ y(0) &= 1, \\ y'(0) &= A \end{aligned} \tag{1}$$

where  $r = r(t)$  is a given function and  $A$  is a constant.

a) Solve this equation using the Laplace transform in the case  $r(t) = 0$ .

b) Determine the solution in the case when  $r(t) = e^t$ .

c) Rewrite the equation (1) for an arbitrary  $r = r(t)$  as a first-order system of the form

$$Z'(t) = F(t, Z)$$

where  $F(t, Z)$  is a vector-valued function and  $Z(t)$  is the unknown vector-valued function to be determined.

d) Write down the classical Runge–Kutta method for this system of equations.

e) Compute the approximate solution  $y(0.1)$  using  $h = 0.1$  in the case  $r(t) = 0$  and  $A = 0$ . Keep 6 digits in the computations.

**Problem 4** Consider the equation  $e^{\frac{x}{3}} - x = 0$ .

- a) Show that this equation has a unique solution in the interval  $(0, 3)$ .
- b) Compute 3 iterations of Newton's method to approximate the solution, starting with  $x_0 = 1$ .
- c) Write the equation as an equation of the form  $g(x) = x$  so that the fixed-point iteration method converges, and compute 3 iterations, starting with  $x_0 = 1$ .

Keep 5 digits in your computations.

**Problem 5** Consider the function  $f(x) = \ln(x)$ .

- a) Compute the Chebyshev points, with  $n = 2$ , in the interval  $[0, 2]$ .
- b) Using Lagrange interpolation, find the polynomial of smallest degree that interpolates the function at the Chebyshev points found in a).

Keep 5 digits in the computations.

**Problem 6** Consider the system of equations

$$\begin{array}{rclcl} 4x_1 & - & x_2 & + & 2x_3 & = & 20 \\ & & - & x_2 & + & 4x_3 & = & 28 \\ -x_1 & + & 4x_2 & - & x_3 & = & -40 \end{array}$$

- a) Rearrange this system of equations so that you can apply Jacobi's method and such that it converges.
- b) Perform 2 iterations of the Jacobi's method, starting with  $\mathbf{x}_0 = (1, 1, 1)$ , using 5 digits in the computations.

**Problem 7** Let  $u(x, t)$  be the temperature at time  $t$  in a laterally insulated bar of length 3 lying on the  $x$ -axis. It satisfies the heat equation

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2}, \quad 0 \leq x \leq 3, \quad t \geq 0,$$

with initial condition

$$u(x, 0) = 2 \sin\left(\frac{\pi x}{3}\right)$$

and boundary conditions

$$u(0, t) = u(3, t) = 0, \quad t \geq 0.$$

- a) Find the solutions that are of the form  $u(x, t) = F(x)G(t)$  and that satisfy the boundary conditions.
- b) Find the solution that satisfies the initial condition. Evaluate  $u(1, 0.5)$ .
- c) Use the Crank–Nicolson method with  $k = 0.5$  and  $h = 1$  to approximate the value of  $u(1, 0.5)$ . Keep 5 digits in the computations.

## Fourier Transform

$f(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \hat{f}(\omega) e^{i\omega x} d\omega$	$\hat{f}(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(x) e^{-i\omega x} dx$
$f * g(x)$	$\sqrt{2\pi} \hat{f}(\omega) \hat{g}(\omega)$
$f'(x)$	$i\omega \hat{f}(\omega)$
$e^{-ax^2}$	$\frac{1}{\sqrt{2a}} e^{-\omega^2/4a}$
$e^{-a x }$	$\sqrt{\frac{2}{\pi}} \frac{a}{\omega^2 + a^2}$
$\frac{1}{x^2 + a^2}$	$\sqrt{\frac{\pi}{2}} \frac{e^{-a \omega }}{a}$
$f(x) = 1$ for $ x  < a$ , 0 otherwise	$\sqrt{\frac{2}{\pi}} \frac{\sin \omega a}{\omega}$

## Laplace Transform

$f(t)$	$F(s) = \int_0^{\infty} e^{-st} f(t) dt$
$f'(t)$	$sF(s) - f(0)$
$tf(t)$	$-F'(s)$
$e^{at} f(t)$	$F(s - a)$
$\cos(\omega t)$	$\frac{s}{s^2 + \omega^2}$
$\sin(\omega t)$	$\frac{\omega}{s^2 + \omega^2}$
$t^n$	$\frac{n!}{s^{n+1}}$
$e^{at}$	$\frac{1}{s - a}$
$f(t - a)u(t - a)$	$e^{-sa} F(s)$
$\delta(t - a)$	$e^{-as}$
$f * g(t)$	$F(s)G(s)$

## Numerics

- Newton's method:  $x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}$ .
- Newton's method for system of equations:  $\vec{x}_{k+1} = \vec{x}_k - JF(\vec{x}_k)^{-1}F(\vec{x}_k)$ , with  $JF = (\partial_j f_i)$ .
- Lagrange interpolation:  $p_n(x) = \sum_{k=0}^n \frac{l_k(x)}{l_k(x_k)} f_k$ , with  $l_k(x) = \prod_{j \neq k} (x - x_j)$ .
- Interpolation error:  $\epsilon_n(x) = \prod_{k=0}^n (x - x_k) \frac{f^{(n+1)}(t)}{(n+1)!}$ .
- Chebyshev points:  $x_k = \cos\left(\frac{2k+1}{2n+2}\pi\right)$ ,  $0 \leq k \leq n$ .
- Newton's divided difference:  $f(x) \approx f_0 + (x - x_0)f[x_0, x_1] + (x - x_0)(x - x_1)f[x_0, x_1, x_2] + \dots + (x - x_0)(x - x_1) \dots (x - x_{n-1})f[x_0, \dots, x_n]$ , with  $f[x_0, \dots, x_k] = \frac{f[x_1, \dots, x_k] - f[x_0, \dots, x_{k-1}]}{x_k - x_0}$ .
- Trapezoid rule:  $\int_a^b f(x) dx \approx h \left[ \frac{1}{2}f(a) + f_1 + f_2 + \dots + f_{n-1} + \frac{1}{2}f(b) \right]$ .  
Error of the trapezoid rule:  $|\epsilon| \leq \frac{b-a}{12} h^2 \max_{x \in [a,b]} |f''(x)|$ .
- Simpson rule:  $\int_a^b f(x) dx \approx \frac{h}{3} [f_0 + 4f_1 + 2f_2 + 4f_3 + \dots + 2f_{n-2} + 4f_{n-1} + f_n]$ .  
Error of the Simpson rule:  $|\epsilon| \leq \frac{b-a}{180} h^4 \max_{x \in [a,b]} |f^{(4)}(x)|$ .
- Gauss–Seidel iteration:  $\mathbf{x}^{(m+1)} = \mathbf{b} - \mathbf{L}\mathbf{x}^{(m+1)} - \mathbf{U}\mathbf{x}^{(m)}$ , with  $\mathbf{A} = \mathbf{I} + \mathbf{L} + \mathbf{U}$ .
- Jacobi iteration:  $\mathbf{x}^{(m+1)} = \mathbf{b} + (\mathbf{I} - \mathbf{A})\mathbf{x}^{(m)}$ .
- Euler method:  $\mathbf{y}_{n+1} = \mathbf{y}_n + h\mathbf{f}(x_n, \mathbf{y}_n)$ .
- Improved Euler method:  $\mathbf{y}_{n+1} = \mathbf{y}_n + \frac{1}{2}h[\mathbf{f}(x_n, \mathbf{y}_n) + \mathbf{f}(x_n + h, \mathbf{y}_{n+1}^*)]$ , where  $\mathbf{y}_{n+1}^* = \mathbf{y}_n + h\mathbf{f}(x_n, \mathbf{y}_n)$ .
- Classical Runge–Kutta method:  $\mathbf{k}_1 = h\mathbf{f}(x_n, \mathbf{y}_n)$ ,  
 $\mathbf{k}_2 = h\mathbf{f}(x_n + h/2, \mathbf{y}_n + \mathbf{k}_1/2)$ ,  $\mathbf{k}_3 = h\mathbf{f}(x_n + h/2, \mathbf{y}_n + \mathbf{k}_2/2)$ ,  
 $\mathbf{k}_4 = h\mathbf{f}(x_n + h, \mathbf{y}_n + \mathbf{k}_3)$ ,  $\mathbf{y}_{n+1} = \mathbf{y}_n + \frac{1}{6}\mathbf{k}_1 + \frac{1}{3}\mathbf{k}_2 + \frac{1}{3}\mathbf{k}_3 + \frac{1}{6}\mathbf{k}_4$ .
- Backward Euler method:  $\mathbf{y}_{n+1} = \mathbf{y}_n + h\mathbf{f}(x_{n+1}, \mathbf{y}_{n+1})$ .
- Finite differences:  $\frac{\partial u}{\partial x}(x, y) \approx \frac{u(x+h, y) - u(x-h, y)}{2h}$ ,  $\frac{\partial^2 u}{\partial x^2}(x, y) \approx \frac{u(x+h, y) - 2u(x, y) + u(x-h, y)}{h^2}$ .
- Crank–Nicolson method for the heat equation:  $r = \frac{k}{h^2}$ ,  
 $(2 + 2r)u_{i,j+1} - r(u_{i+1,j+1} + u_{i-1,j+1}) = (2 - 2r)u_{ij} + r(u_{i+1,j} + u_{i-1,j})$ .