



**NTNU – Trondheim**  
Norwegian University of  
Science and Technology

Department of Mathematical Sciences

## Examination paper for **TMA4125 Calculus 4N**

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**Examination date:** May 29th 2017

**Examination time (from–to):** 09:00–13:00

**Permitted examination support material:** Kode C:

Bestemt, enkel kalkulator

Rottmann: Matematisk formelsamling

### **Other information:**

- All answers have to be justified, and they should include enough details in order to see how they have been obtained.
- All numbered problems carry the same weight for grading.
- Good luck!

**Language:** English

**Number of pages:** 3

**Number of pages enclosed:** 2

**Checked by:**

Informasjon om trykking av eksamensoppgave

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**Problem 1** Let  $f : [0, 2] \rightarrow \mathbb{R}$  be given by

$$f(x) = \begin{cases} 0 & \text{for } 0 < x \leq 1 \\ 1 - x & \text{for } 1 < x \leq 2 \end{cases}$$

Let  $g : \mathbb{R} \rightarrow \mathbb{R}$  be the odd 4-periodic extension of  $f$ . Sketch its graph on the interval  $[-6, 6]$  and compute the Fourier series of  $g$ .

**Problem 2** Use Laplace transformations to solve the integro-differential equation

$$y' = 2 \sin t + \int_0^t y(\tau) \cos(t - \tau) d\tau,$$

with initial value  $y(0) = 1$ .

**Problem 3**

**a)** Let  $a < b$  be real numbers, and  $\hat{g}(w)$  be the Fourier transform of  $g(x)$ . Derive the identity

$$\frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \frac{\hat{g}(w)(e^{iwb} - e^{iwa})}{iw} dw = \int_a^b g(x) dx$$

**b)** Take Fourier transforms with respect to  $x$  on both sides of the wave equation

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2}$$

Suppose we wish to solve the equation with respect to the initial conditions  $u(x, 0) = 0$ ,  $u_t(x, 0) = g(x)$ . By solving the equation for  $\hat{u}$ , show that the Fourier transform of  $u$  is given by

$$\hat{u}(w, t) = \frac{\hat{g}(w)}{cw} \sin cwt$$

**c)** Deduce from the above that

$$u(x, t) = \frac{1}{2c} \int_{x-ct}^{x+ct} g(x) dx$$

**Problem 4**

- a) The steady state temperature of a plate of dimension  $2 \times 1$  (in metres) is modeled by the equation

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0,$$

for  $0 \leq x \leq 2$ ,  $0 \leq y \leq 1$ . The right hand side of the plate is insulated, whilst the left hand side is held at a constant temperature of  $0^\circ\text{C}$ , i.e.

$$u(0, y) = u_x(2, y) = 0,$$

Find all possible solutions  $u(x, y) = F(x)G(y)$  of the equation satisfying the above conditions.

- b) If the bottom edge of the plate is also insulated, i.e.  $u_y(x, 0) = 0$ , and the top edge is held at temperature

$$u(x, 1) = (50 \sin \frac{5\pi x}{4})^\circ\text{C},$$

solve the equation to find the steady state temperature  $u(x, y)$  of the plate.

**Problem 5** Consider the system of linear equations

$$4x_1 + 2x_3 = 3$$

$$2x_2 + x_3 = -1$$

$$2x_1 + x_2 + 4x_3 = 2$$

Find an approximation to the solution of the above system by computing two steps of the Gauss-Seidel iteration. Use  $x_1 = x_2 = x_3 = 0$  as the initial value.

**Problem 6** Let  $f(x) = \tan(x)$ .

- a) Find a numerical approximation to

$$\int_0^1 f(x) dx$$

by using Simpson's rule with  $2n = 4$  integration intervals.

- b) It may be shown that  $|f^{(4)}(x)| \leq 12$  on  $x \in [0, 1]$ . How many integration intervals do we require to ensure that the error of the Simpson's rule approximation is less than  $10^{-6}$ ?

**Problem 7** Consider the differential equation

$$y'(t) = t^2 \sin(y(t)), \quad y(0) = 1$$

Find an approximation to  $y(2)$  by applying the backward Euler method with  $h = 2$  and solving the resulting nonlinear equation using two iterations of Newton's method (use the value of  $y(0)$  as the initial value for the Newton iterations).

**Problem 8** Consider the differential equation

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} + 8u, \quad 0 < x < 1, t > 0$$

with boundary conditions  $u(0, t) = 1$ ,  $u(1, t) = 0$  and initial condition  $u(x, 0) = 1 - x$ .

Formulate the Crank-Nicolson method for the numerical solution of the equation. Use step sizes  $h = 0.25$  in the  $x$ -direction and  $k = 0.25$  in the  $t$ -direction, and perform two time-steps.

## Fourier

$f(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \hat{f}(\omega) e^{i\omega x} d\omega$	$\hat{f}(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(x) e^{-i\omega x} dx$
$f * g(x)$	$\sqrt{2\pi} \hat{f}(\omega) \hat{g}(\omega)$
$f'(x)$	$i\omega \hat{f}(\omega)$
$e^{-ax^2}$	$\frac{1}{\sqrt{2a}} e^{-\omega^2/4a}$
$e^{-a x }$	$\sqrt{\frac{2}{\pi}} \frac{a}{\omega^2 + a^2}$
$\frac{1}{1+x^2}$	$\sqrt{\frac{\pi}{2}} e^{- \omega }$
$f(x) = 1$ for $ x  < a$ , 0 otherwise	$\sqrt{\frac{2}{\pi}} \frac{\sin \omega a}{\omega}$

## Laplace transform

$f(t)$	$F(s) = \int_0^{\infty} e^{-st} f(t) dt$
$f'(t)$	$sF(s) - f(0)$
$tf(t)$	$-F'(s)$
$e^{at} f(t)$	$F(s - a)$
$\cos(\omega t)$	$\frac{s}{s^2 + \omega^2}$
$\sin(\omega t)$	$\frac{\omega}{s^2 + \omega^2}$
$t^n$	$\frac{n!}{s^{n+1}}$
$e^{at}$	$\frac{1}{s - a}$
$f(t - a)u(t - a)$	$e^{-sa} F(s)$
$\delta(t - a)$	$e^{-as}$
$f * g(t)$	$F(s)G(s)$

## Numerics

- Newton's method:  $x_{k+1} = x_k - f(x_k)/f'(x_k)$ .

- Newton's method for systems:  $\mathbf{J}^{(k)}(\mathbf{x}^{(k+1)} - \mathbf{x}^{(k)}) = -\mathbf{f}(\mathbf{x}^{(k)})$  with  $(\mathbf{J}^{(k)})_{ij} = \partial_j f_i^{(k)}$
- Lagrange interpolation polynomial:  $L_k(x) = \frac{(x-x_0)\cdots(x-x_{k-1})(x-x_{k+1})\cdots(x-x_n)}{(x_k-x_0)\cdots(x_k-x_{k-1})(x_k-x_{k+1})\cdots(x_k-x_n)}$ ,  
 $p_n(x) = \sum_{k=0}^n L_k(x)f(x_k)$
- Trapezoid rule:  $\int_a^b f(x) dx \approx h \left[ \frac{1}{2}f(a) + f(x_1) + f(x_2) + \dots + f(x_{n-1}) + \frac{1}{2}f(b) \right]$   
 Error of the trapezoid rule:  $|\epsilon| \leq h^2 \frac{b-a}{12} \max_{a \leq x \leq b} |f''(x)|$ .
- Simpson rule:  $\int_a^b f(x) dx \approx \frac{h}{3} [f_0 + 4f_1 + 2f_2 + 4f_3 + \dots + 2f_{n-2} + 4f_{n-1} + f_n]$   
 with  $f_i = f(x_i)$ .  
 Error of the Simpson rule:  $|\epsilon| \leq h^4 \frac{b-a}{180} \max_{a \leq x \leq b} |f^{(4)}(x)|$ .
- Gauss–Seidel iteration:  $\mathbf{x}^{(k+1)} = \mathbf{b} - \mathbf{L}\mathbf{x}^{(k+1)} - \mathbf{U}\mathbf{x}^{(k)}$  with  $\mathbf{A} = \mathbf{I} + \mathbf{L} + \mathbf{U}$ .
- Jacobi iteration:  $\mathbf{x}^{(k+1)} = \mathbf{b} + (\mathbf{I} - \mathbf{A})\mathbf{x}^{(k)}$
- Euler method:  $\mathbf{y}_{n+1} = \mathbf{y}_n + h\mathbf{f}(t_n, \mathbf{y}_n)$
- Improved Euler method:  $\mathbf{k}_1 = h\mathbf{f}(t_n, \mathbf{y}_n)$ ,  $\mathbf{k}_2 = h\mathbf{f}(t_n + h, \mathbf{y}_n + \mathbf{k}_1)$ ,  
 $\mathbf{y}_{n+1} = \mathbf{y}_n + \frac{1}{2}\mathbf{k}_1 + \frac{1}{2}\mathbf{k}_2$ .
- Classical Runge–Kutte method:  
 $\mathbf{k}_1 = h\mathbf{f}(t_n, \mathbf{y}_n)$ ,  $\mathbf{k}_2 = h\mathbf{f}(t_n + h/2, \mathbf{y}_n + \mathbf{k}_1/2)$ ,  
 $\mathbf{k}_3 = h\mathbf{f}(t_n + h/2, \mathbf{y}_n + \mathbf{k}_2/2)$ ,  $\mathbf{k}_4 = h\mathbf{f}(t_n + h, \mathbf{y}_n + \mathbf{k}_3)$ ,
- Backward Euler method:  $\mathbf{y}_{n+1} = \mathbf{y}_n + h\mathbf{f}(t_{n+1}, \mathbf{y}_{n+1})$
- Finite differences:  $\frac{\partial u}{\partial x}(x, y) \approx \frac{u(x+h, y) - u(x-h, y)}{2h}$   
 $\frac{\partial^2 u}{\partial x^2}(x, y) \approx \frac{u(x+h, y) - 2u(x, y) + u(x-h, y)}{h^2}$   
 $\frac{\partial u}{\partial y}(x, y) \approx \frac{u(x, y+h) - u(x, y-h)}{2h}$   
 $\frac{\partial^2 u}{\partial y^2}(x, y) \approx \frac{u(x, y+h) - 2u(x, y) + u(x, y-h)}{h^2}$