

Exercise #12

31. March 2025

Exercises marked with a (J) should be handed in as or together with a Jupyter notebook.

Optional exercises will not be corrected

Problem 1. (Lipschitz continuity)

Determine whether the following functions are Lipschitz continuous for all $t, y \in \mathbb{R}$.

a) $f(t, y) = e^{-t^2} y$.

b) $f(t, y) = \frac{t^2 y}{1 + t^2}$.

Problem 2. (4th order Runge-Kutta - (J))

The classical 4th order Runge-Kutta method is given as

$$\begin{aligned} \mathbf{k}_1 &= \mathbf{f}(t_n, \mathbf{y}_n) \\ \mathbf{k}_2 &= \mathbf{f}\left(t_n + \frac{h}{2}, \mathbf{y}_n + \frac{h}{2}\mathbf{k}_1\right) \\ \mathbf{k}_3 &= \mathbf{f}\left(t_n + \frac{h}{2}, \mathbf{y}_n + \frac{h}{2}\mathbf{k}_2\right) \\ \mathbf{k}_4 &= \mathbf{f}(t_n + h, \mathbf{y}_n + h\mathbf{k}_3) \\ \mathbf{y}_{n+1} &= \mathbf{y}_n + \frac{h}{6}(\mathbf{k}_1 + 2\mathbf{k}_2 + 2\mathbf{k}_3 + \mathbf{k}_4). \end{aligned}$$

- a) Implement this method in Python.
- b) Verify numerically that this method has convergence order $p = 4$.

You may use the example problem

$$\begin{aligned} y' &= -2ty, \\ y(0) &= 1. \end{aligned}$$

Recall that the analytic solution of such problem is $y(t) = e^{-t^2}$.

Problem 3. (Numerical solution of ODEs - (J))

In this problem we will implement Euler's method, second order Taylor's method, and Heun's method, and use them to approximate the solution to the ODE,

$$y' = -ty + \sin(t), \quad y(0) = 2.$$

The exact solution to this equation is $y(t) = e^{-t^2/2} \left(2 + \int_0^t e^{s^2/2} \sin(s) ds \right)$. You can use the notebook `numerical-ode-3.ipynb` as a starting point.

- a) Implement Euler's method, and compute an approximation of $y(1)$, using a step size equal to 0.1.
- b) Do the same using Heun's method and the second order Taylor method. The second order Taylor method is given by

$$y_{n+1} = y_n + hf(t_n, y_n) + \frac{h^2}{2} f'(t_n, y_n),$$

where $f(t, y) = y'(t) = -ty + \sin(t)$ and thus $f'(t, y) := \frac{d}{dt}f(t, y) = \frac{d}{dt}(-ty + \sin(t))$.

- c) We now want to approximate the convergence orders of these methods numerically. Recall that we defined the global error,

$$\varepsilon_g := \max_n |y(t_n) - y_n|.$$

If we assume that $\varepsilon_g(h) \approx Mh^p$, for some $M > 0$, we have,

$$\log \left(\frac{\varepsilon_g(h_1)}{\varepsilon_g(h_2)} \right) \approx p \log \left(\frac{h_1}{h_2} \right).$$

Compute the global error of the methods from a)-b) using $h_1 = 10^{-2}$ and $h_2 = 10^{-3}$, where $t_n = nh$, $n = 0, \dots, \frac{1}{h}$. Use this to approximate the convergence order, p , for each of the three methods.

- d) We can also approximate the convergence order by plotting $\log(\varepsilon_g(h)) = \log(M) + p \log(h)$ versus $\log(h)$, and inspecting the slope of the function.

Plot $\log(\varepsilon_g(h))$ versus $\log(h)$ for $h = 10^{-2}, 10^{-3}, 10^{-4}$ for each of the three methods.

Problem 4. (Runge–Kutta method - (J))

In this exercise we will study a Runge–Kutta method that is given by

$$\begin{aligned}k_1 &= f(t_n, y_n) \\k_2 &= f\left(t_n + \frac{h}{3}, y_n + \frac{k_1}{3}\right) \\k_3 &= f\left(t_n + \frac{2}{3}h, y_n - \frac{1}{3}k_1 + k_2\right) \\k_4 &= f\left(t_n + h, y_n + k_1 - k_2 + k_3\right) \\y_{n+1} &= y_n + \frac{h}{8}(k_1 + 3k_2 + 3k_3 + k_4)\end{aligned}$$

- a) Present the method in the form of a Butcher tableau.
- b) Decide the order of the method.
- c) Implement this method in Python.
- d) Verify the convergence order numerically. For this you can use the example problem

$$y' = 2ty, \quad y(0) = 1,$$

which has the analytical solution $y(t) = e^{t^2}$, on the interval $[0, 1]$.

The next exercises are optional and should not be handed in!

Problem 5. (System of ODEs)

Write the second order linear ODE,

$$\begin{aligned}2y + y' + y'' + 1 &= 0, \\ y(0) &= 0, \\ y'(0) &= 2,\end{aligned}$$

as a linear system of first order ODEs, and perform one step of Euler's method with step size 1.

Solution.

We start by setting $w_1 = y$ and $w_2 = y'$. Inserted into the ODE, this gives

$$\begin{aligned}w_1' &= w_2 \\ w_2' &= -2w_1 - w_2 - 1.\end{aligned}$$

This can be expressed by

$$\mathbf{w}' = A\mathbf{w} + \mathbf{b},$$

where

$$\mathbf{w} = \begin{pmatrix} w_1 \\ w_2 \end{pmatrix}, \quad A = \begin{pmatrix} 0 & 1 \\ -2 & -1 \end{pmatrix}, \quad \mathbf{b} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}.$$

Also $\mathbf{w}(0) = (0, 2)$. One step of Euler's method with step size 1 in this case gives

$$\mathbf{w}_1 = \mathbf{w}(0) + A\mathbf{w}(0) + \mathbf{b} = \begin{pmatrix} 0 \\ 2 \end{pmatrix} + \begin{pmatrix} 2 \\ -2 \end{pmatrix} + \begin{pmatrix} 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \end{pmatrix}.$$

Problem 6. (Implementation of an ODE solver)

```
import numpy as np

f = lambda t,y : 2/t**2*y
t0, tend = 1, 2
y0 = 1
N = 10

y = np.zeros(N+1)
t = np.zeros(N+1)
y[0] = y0
t[0] = a

for n in range(N):
    k1 = f(t[n],y[n])
    k2 = f(t[n]+0.5*h, y[n]+0.5*h*k1)
    y[n+1] = y[n] + h*k2

print('t=',t)
print('y=',y)
```

- There are three bugs in this code. Two that prevent it from running at all, and one which causes a completely nonsense output. Find and correct the errors.
- Which mathematical problem does this code intend to solve numerically?
- Which specific algorithm has been applied to the problem? No specific name is required, but present the method in the form of a Butcher tableau, and decide the order of the method.
- Find the first two elements of the NumPy vector y , given that point a) is accomplished.

Solution.

```
import numpy as np

f = lambda t,y : 2/ t**2*y
t0, tend = 1, 2
y0 = 1
N = 10

y = np.zeros(N + 1)
t = np.zeros(N + 1)
y[0] = y0
t[0] = t0                                #Assigning a starting time
h = (tend-t0)/N                          #Need to define h

for n in range (N):
    k1 = f(t[n],y[n])
    k2 = f(t[n]+0.5* h , y[n]+0.5* h * k1)
    y[n+1] = y[n] + h*k2
    t[n+1] = t[n] + h                    #Need to update timestep

print('t=',t)
print('y=',y)
```

a) The corrected version is written above, with comments for where the code is changed. The errors that made the code not run were that $t[0]$ was not set to t_0 but to some undefined variable a and that h was not defined. In addition, there were no computations of new timesteps, which made the output wrong.

b) This problem tries to solve the initial value problem

$$y' = \frac{2}{t^2} y, \quad y(1) = 1,$$

on the interval $[1, 2]$.

c) The method presented as a Butcher tableau:

0	0	0
$\frac{1}{2}$	$\frac{1}{2}$	0
<hr/>		
	0	1

This method is known as the explicit midpoint method. Next, we check the order conditions:

$p = 1$	$b_1 + b_2 = 0 + 1 = 1$	OK
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$p = 2$	$b_1c_1 + b_2c_2 = 0 + 1 \cdot \frac{1}{2} = \frac{1}{2}$	OK
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$p = 3$	$b_1c_1^2 + b_2c_2^2 = 0 + 1^2 \cdot \frac{1^2}{2^2} = \frac{1}{4} \neq \frac{1}{3}$	Not satisfied
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We see that up to $p = 2$, the conditions are satisfied. The method is therefore of order 2.

d) If we run the code, we get that the first two elements of y are 1. and 1.19954649.