PROBLEM SET 11.4

1. **(Calculus review)** Review complex numbers.
2. **(Even and odd functions)** Show that the complex Fourier coefficients of an even function are real and those of an odd function are pure imaginary.
3. **(Fourier coefficients)** Show that $a_0 = c_0$, $a_n = c_n + c_{-n}$, $b_n = i(c_n - c_{-n})$.
4. Verify the calculations in Example 1.
5. Find further terms in (9) and graph partial sums with your CAS.
6. Obtain the real series in Example 1 directly from the Euler formulas in Sec. 11.

7–13 COMPLEX FOURIER SERIES

Find the complex Fourier series of the following functions. (Show the details of your work.)

7. $f(x) = -1$ if $-\pi < x < 0$, $f(x) = 1$ if $0 < x < \pi$
8. Convert the series in Prob. 7 to real form.
9. $f(x) = x \quad (-\pi < x < \pi)$
10. Convert the series in Prob. 9 to real form.
11. $f(x) = x^2 \quad (-\pi < x < \pi)$
12. Convert the series in Prob. 11 to real form.
13. $f(x) = x \quad (0 < x < 2\pi)$
14. **PROJECT. Complex Fourier Coefficients.** It is very interesting that the c_n in (6) can be derived directly by a method similar to that for a_n and b_n in Sec. 11.1. For this, multiply the series in (6) by e^{-imx} with fixed integer m, and integrate termwise from $-\pi$ to π on both sides (allowed, for instance, in the case of uniform convergence) to get

$$\int_{-\pi}^{\pi} f(x)e^{-imx}\,dx = \sum_{n=-\infty}^{\infty} c_n \int_{-\pi}^{\pi} e^{i(n-m)x}\,dx.$$

Show that the integral on the right equals 2π when $n = m$ and 0 when $n \neq m$ [use (3b)], so that you get the coefficient formula in (6).

11.5 Forced Oscillations

Fourier series have important applications in connection with ODEs and PDEs. We show this for a basic problem modeled by an ODE. Various applications to PDEs will follow in Chap. 12. This will show the enormous usefulness of Euler's and Fourier's ingenious idea of splitting up periodic functions into the simplest ones possible.

From Sec. 2.8 we know that forced oscillations of a body of mass m on a spring of modulus k are governed by the ODE

$$my'' + cy' + ky = r(t) \tag{1}$$

where $y = y(t)$ is the displacement from rest, c the damping constant, k the spring constant (spring modulus), and $r(t)$ the external force depending on time t. Figure 271 shows the model and Fig. 272 its electrical analog, an RLC-circuit governed by

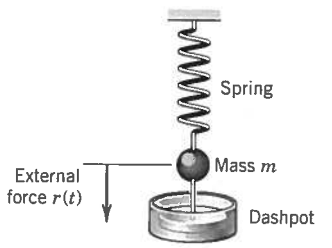

Fig. 271. Vibrating system under consideration

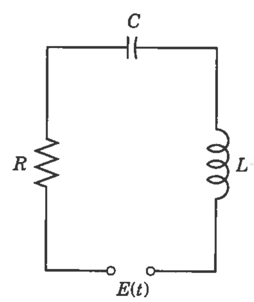

Fig. 272. Electrical analog of the system in Fig. 271 (*RLC*-circuit)