



- 1 About the Lipschitz condition, the one-sided Lipschitz-condition, and logarithmic norms.

In this exercise, only the 2-norm is considered. We will also for simplicity assume that all conditions are valid for all $y, v \in \mathbb{R}^m$ and all relevant intervals $t \in (t_0, t_{end})$.

- a) Consider the system of equations

$$\begin{aligned}y_1' &= -100y_1 + y_2, & y_1(0) &= 1 \\y_2' &= y_1 - 100y_2, & y_2(0) &= 0\end{aligned}\quad (1)$$

Find the exact solution of the problem.

For ODEs $y' = f(t, y)$ we have the following well known result:

$$\|f(t, y) - f(t, v)\| \leq L\|y - v\| \quad \Rightarrow \quad \|y(t) - v(t)\| \leq e^{L(t-t_0)}\|y(t_0) - v(t_0)\|, \quad t > t_0$$

- b) Use this to find a bound for $\|y(1) - v(1)\|_2$ when $v(t)$ is the solution of the ODE (1) with initial values $v_1(0) = 1, v_2(0) = 1/10$.

The function $f(t, y)$ satisfies a *one-sided Lipschitz condition* if, for all t ,

$$\langle f(t, y) - f(t, v), y - v \rangle_2 \leq \mu\|u - v\|_2^2, \quad \forall u, v \in \mathbb{R}^m. \quad (2)$$

where μ is called a one-sided Lipschitz constant. It can be proved that if (2) is satisfied, then

$$\|y(t) - v(t)\|_2 \leq e^{\mu(t-t_0)}\|y(t_0) - v(t_0)\|_2, \quad t > t_0 \quad (3)$$

see Theorem 2.4 in the *Lecture notes on the numerical solution of ODEs*. Further, it can be proved that if $f(t, y) = Ay$, then the smallest possible one-sided Lipschitz constant for f is the logarithmic norm

$$\mu_2(A) = \lim_{h \rightarrow 0, h > 0} \frac{\|I + hA\|_2 - 1}{h} \quad (4)$$

and in particular that

$$\mu_2(A) = \lambda_{\max} \left(\frac{A + A^T}{2} \right) \quad (5)$$

- c) Use (3) to find a better bound for $\|y(1) - v(1)\|_2$ of b). Compare with the exact solution.
- d) (Optional) Prove the statements related to (4) and (5).

2 About the practical use of B-series and rooted trees

- a) Kutta's method from 1901 is definitely the most famous of all explicit Runge–Kutta pairs. Its Butcher tableau is given by

$$\begin{array}{c|ccc}
 0 & & & \\
 \frac{1}{2} & \frac{1}{2} & & \\
 \frac{1}{2} & 0 & \frac{1}{2} & \\
 1 & 0 & 0 & 1 \\
 \hline
 & \frac{1}{6} & \frac{1}{3} & \frac{1}{3} & \frac{1}{6}
 \end{array}$$

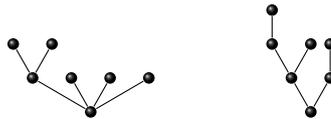
Verify that the method is of order 4 by confirming that it obeys all the eight order conditions.

- b) Show that an explicit Runge–Kutta method of order 3 with 3 stages has to satisfy

$$3 a_{32} c_2^2 - 2 a_{32} c_2 - c_2 c_3 + c_3^2 = 0. \tag{6}$$

- c) Characterize all 3rd-order explicit Runge–Kutta methods with 3 stages which satisfy $a_{31} = 0$, that is, which satisfy $a_{32} = c_3$. How many free parameters are there?

- d) Write down the order conditions corresponding to the following rooted trees:



Also, write down the order of the trees.

Hint: Use the result (7) of the next exercise.

3 In the lecture note, it is proved that the B-series of the exact solution of the ODE $y' = f(y)$ can be written as

$$y(t_0 + h) = B(e, y_0; h), \quad \text{with} \quad e(\tau)(h) = \frac{1}{\gamma(\tau)} h^{\rho(\tau)}.$$

Show that

$$\gamma(\bullet) = 1, \quad \gamma(\tau) = \rho(\tau) \prod_{i=1}^{\kappa} \gamma(\tau_i), \quad \text{when} \quad \tau = [\tau_1, \tau_2, \dots, \tau_{\kappa}]. \tag{7}$$

At this point, it could also be a good idea to compare our definition of B-series with the definition used in GNI, III.1, def.1.8.

4 For a better understanding of the B-series

- a) Consider ODEs of the form

$$y' = y^2$$

For which trees $\tau \in T$ will the elementary differentials $F(\tau)(y) = 0$?

What if

$$y' = Ay + g(t), \quad A \text{ constant matrix?}$$

b) (Optional) Derive a B-series for the exact solution of a split ODE:

$$y' = f(y) + g(y).$$

Hint: You may need bi-colored trees, one color for each of f and g .