

Introduction to Lie theory

Material for week 11

Alexander Schmeding

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3.1 The Lie algebra of a Lie group

Lie groups and their algebras

A Lie group G is a manifold G endowed with a group structure such that the multiplication map $m_G: G \times G \rightarrow G$ and the inversion map $\iota: G \rightarrow G$ are smooth. A vector field X on G is called left-invariant if

$$T\lambda_g \circ X = X \circ \lambda_g \quad g \in G.$$

The Lie algebra of G

$\mathbf{L}(G) = T_1G$ with Lie bracket induced by the linear isomorphism

$$\Theta: T_1G \rightarrow \mathcal{V}^\ell(G), \quad \Theta(v) = (g \mapsto T\lambda_g(v))$$

We write shorter $v_\ell := \Theta(v)$ for the left-invariant vector field, then the Lie bracket is defined as $[v, w] = [v_\ell, w_\ell](\mathbf{1})$

Examples

3.1.4 Example

The Lie algebra of the abelian Lie group $(\mathbb{R}^n, +)$ is the abelian Lie algebra \mathbb{R}^n .

3.1.5 Example

The linear Lie group $GL_n(\mathbb{K})$ is open in $M_n(\mathbb{K})$, so $T_1 GL_n(\mathbb{K}) = M_n(\mathbb{K}) = \mathfrak{gl}_n(\mathbb{K})$. We already computed the left invariant vector field associated to $X \in M_n(\mathbb{K})$:

$$X_\ell(A) = (A, AX), A \in GL_n(\mathbb{K}).$$

Hence with $\tilde{X}_\ell(A) = AX$ the Lie bracket turns out to be

$$[X, Y] = [X_\ell, Y_\ell](I_n) = \mathbf{d}\tilde{Y}_\ell(I_n)(X) - \mathbf{d}\tilde{X}_\ell(I_n)(Y) = YX - XY$$

Hence we recover the commutator bracket!

From Lie group morphism to Lie algebra morphism

Recall that for a morphism $\varphi: G_1 \rightarrow G_2$ of linear Lie groups we constructed a Lie algebra morphism

$$\mathbf{L}(\varphi)(x) := \left. \frac{d}{dt} \right|_{t=0} \varphi(\exp_{G_1}(tx))$$

Since the Lie group exponential is just the matrix exponential we saw that it induces a chart around the identity.

So the above formula tries to compute the derivative of φ at $\mathbf{1}$!

We can emulate this (without the matrix exponential) as

$$\mathbf{L}(\varphi) = T_{\mathbf{1}}\varphi$$

3.2 The Lie group exponential

3.2.2 Definition

Define the *Lie group exponential* for a Lie group G as

$$\exp_G: \mathbf{L}(G) \rightarrow G, \quad \exp_G(x) := \gamma_x(\mathbf{1}),$$

where $\gamma_x: \mathbb{R} \rightarrow G$ is the unique maximal integral curve of the left invariant vector field x_ℓ , satisfying $\gamma_x(0) = \mathbf{1}$. This means that γ_x is the unique solution of the initial value problem

$$\gamma(0) = \mathbf{1}, \quad \frac{d}{dt}\gamma(t) = x_\ell(\gamma(t)) = T_{\mathbf{1}}\lambda_{\gamma(t)}(x), \quad \forall t \in \mathbb{R}.$$

3.2.3 Example $G = \mathbf{GL}_n(\mathbb{K})$

Left invariant vector fields are of the form

$$X_\ell(A) = (A, AX), \quad \text{i.e. the ODE reads } \dot{\gamma}(t) = \gamma(t)X$$

which is solved by $\gamma(t) = e^{tX}$ i.e. Lie group exponential is the matrix exponential.

3.2.4 Lemma (Properties of the exponential)

Let G be a Lie group. For each $x \in \mathbf{L}(G)$,

1. the curve $\gamma_x: \mathbb{R} \rightarrow G, \gamma_x(t) = \exp_G(tx)$ is a smooth homomorphism of Lie groups with $\gamma'_x(0) = x$.
2. The global flow of the left invariant vector field x_ℓ is given by

$$\text{Fl}^{x_\ell}(t, g) = g\gamma_x(t) = g \exp_G(tx).$$

3. If $\gamma: \mathbb{R} \rightarrow G$ is a smooth homomorphism of Lie groups and $\dot{\gamma}(0) = x$, then $\gamma = \gamma_x$. In particular, the map $\text{Hom}(\mathbb{R}, G) \rightarrow \mathbf{L}(G), \gamma \mapsto \dot{\gamma}(0)$ is a bijection (here $\text{Hom}(\mathbb{R}, G)$ denotes the set of smooth homomorphisms of Lie groups $\mathbb{R} \rightarrow G$).

3.2.5. Naturality of \exp_G

Let $\varphi: G_1 \rightarrow G_2$ be a morphism of Lie groups and $\mathbf{L}(\varphi): \mathbf{L}(G_1) \rightarrow \mathbf{L}(G_2)$ its differential at $\mathbf{1}$. Then

$$\exp_{G_2} \circ \mathbf{L}(\varphi) = \varphi \circ \exp_{G_1} .$$

3.2.6. Lemma

For a Lie group G , the Lie group exponential $\exp_G: \mathbf{L}(G) \rightarrow G$ is smooth and satisfies $T_0 \exp_G = \text{id}_{\mathbf{L}(G)}$.

In particular, \exp_G is a local diffeomorphism at 0 in the sense that it maps some 0-neighborhood in $\mathbf{L}(G)$ diffeomorphically onto some $\mathbf{1}_G$ -neighborhood in G .

3.2.8 Proposition (Lie-Trotter formula)

Let G be a Lie group and $x, y \in \mathbf{L}(G)$ then

$$\exp_G(x + y) = \lim_{k \rightarrow \infty} \left(\exp_G \left(\frac{x}{k} \right) \exp_G \left(\frac{y}{k} \right) \right)^k.$$

3.2.9 Canonical coordinates

Let G be a Lie group and b_1, \dots, b_n be a basis for $\mathbf{L}(G)$. Then the following maps restrict to diffeomorphisms of some 0-neighborhood in \mathbb{R}^n to some open $\mathbf{1}_G$ -neighborhood in G :

- (i) $x \mapsto \exp_G(x_1 b_1 + \dots + x_n b_n)$ (coordinates of the first kind)
- (ii) $x \mapsto \exp_G(x_1 b_1) \cdots \exp_G(x_n b_n)$ (coordinates of the second kind).