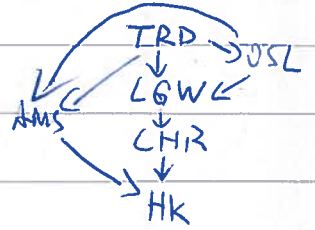


①

§13 Optimization

• Weighted graphs (directed/undi/multi)

• e.g. distance (real dist) vertex=city
 travel cost edge=road/airline/...
 travel time
 capacity



• Ques: shortest distance (on the graph)
 spanning tree
 (Hamilton Paths/Cycles)

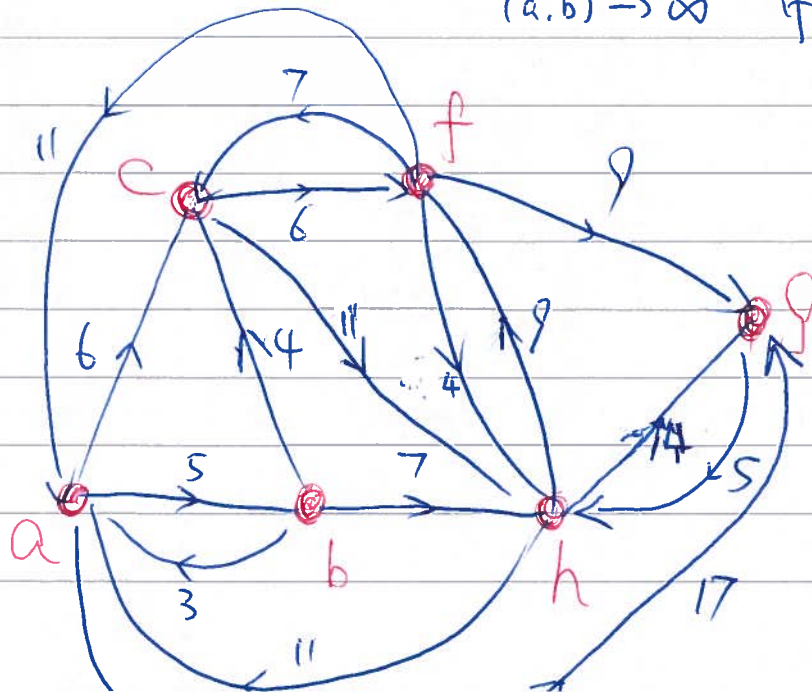
post man

§13.1 Shortest-Path Algorithm

• $G=(V, E)$ loop-free directed (non-multi)

weight is a function: $w_t: E \rightarrow \mathbb{R}_{\geq 0}$

\rightsquigarrow extension to $w_t: V \times V \rightarrow \mathbb{R}_{\geq 0} \cup \{\infty\} = \overline{\mathbb{R}}_{\geq 0}$
 $(a, b) \rightarrow w_t(e)$ if $\exists e: a \rightarrow b$
 $(a, b) \rightarrow \infty$ if $\nexists e: a \rightarrow b$



2

Recall A path p $a \rightsquigarrow b$ is

$$a = v_0 \xrightarrow{e_1} v_1 \xrightarrow{e_2} v_2 \rightarrow \dots \xrightarrow{e_n} v_n = b.$$

(weighted)

• Length of $p = wt(e_1) + \dots + wt(e_n)$

• distance function: $d: V \times V \rightarrow \overline{\mathbb{R}_{\geq 0}}$

$$d(a, b) = \min_{p: a \rightsquigarrow b} \text{length of } p$$

∞ if \nexists path $a \rightsquigarrow b$.

Aim Fix $v_0 \in V$ & determine $d(v_0, v) \quad \forall v \in V$

Alg: Greedy Algorithm (general algo.)

principle is to achieve "min" locally
& hence globally

Find the
closest vertex
from the
rest vertices

• Dijkstra's:

Step 1) Set $i=0$, $S_0 = \{v_0\}$. Label v_0 with $(0, -)$
& $v \neq v_0$ with $(\infty, -)$

If $n=1$ then \square else \rightarrow

Step 2) For each $v \in \overline{S_i}$, replace the label (if possible)
on v by $(L(v), y)$ where

$$L(v) = \min_{u \in S_i} \{L(u), L(u) + wt(u, v)\}$$

& y is the vertex in S_i that produces min $L(v)$ above.

Step 3) If $\forall v \in \overline{S_i}$ is labeled with $(\infty, -)$. \square

3

Otherwise:

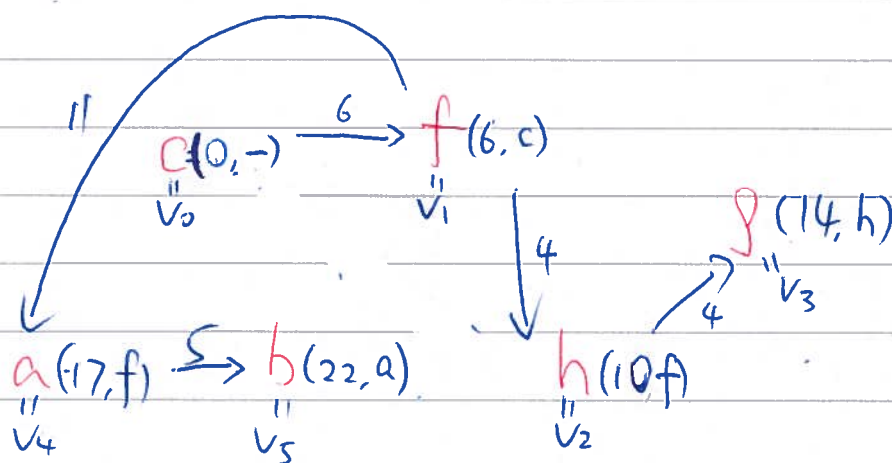
3.1) Choose $v_{i+1} \in \bar{S}_i$ s.t. $L(v_{i+1})$ is min among \bar{S}_i .

(so v_{i+1} is the vertex in \bar{S}_i that is closest to v_0)

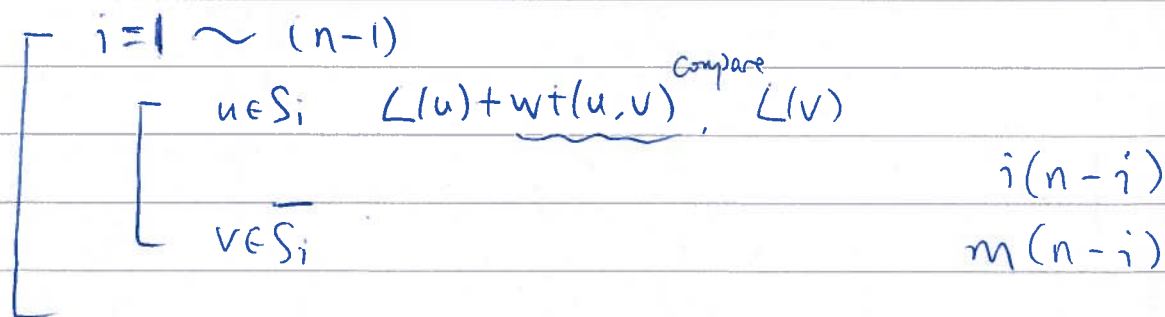
3.2) $S_{i+1} = S_i \cup \{v_{i+1}\}$.

3.3) $i = i + 1$. If $i = n - 1$ \square otherwise back to 2).

Ex: $c = v_0$



• Complexity (worst-case).



$$\sum_{i=1}^{n-1} i(n-i) = \sum_{i=1}^{n-1} i n - \sum_{i=1}^{n-1} i^2 \sim O(n^3).$$

$$\boxed{O(m \log_2 n)} \leftarrow O(mn) \leftarrow O(n^2)$$

④

• $L(v)$

$v_i = i$ th-closest vertex

$S_i = \{v_0, \dots, v_i\}$.

• $L(v_0) = 0$, $L(v) = \infty$ $v \neq v_0$. $S_0 = \{v_0\}$.

$i \geq 0$. $v \in S_i$

$$L_{i+1}(v) = \min \{ L_i(v), L_i(v_i) + w(v_i, v) \}$$

$$= \min_{1 \leq j \leq i} \{ d(v_0, v_j) + w(v_j, v) \}$$

$v_{i+1} = v \in S_i$ s.t. $L_{i+1}(v)$ minimalizes.

• Complexity $\sum_{i=1}^{n-1} 3(n-i) \sim O(n^2)$

①

4.9.

§13.2 Minimal Spanning Tree.

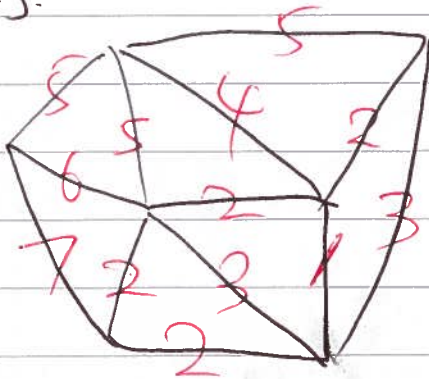
• Scenario: To set up a network of computers.

$G=(V, E)$ V {computers} $w_t(E)$ = cost to build a connection

Aim: spent minimal cost

e.g.

to get a connected network.



The resulting subgraph is a tree

(? otherwise delete v edge into cycles)

(no edge \Leftrightarrow cost = ∞)

Def. MST is a tree $T \subset G$ s.t. it is spanning, connected & $w_t(T) = \sum_{e \in T} w_t(e)$ is minimal.

Idea 1. Use shortest edges first!



Kruskal's algorithm:

Step 1 Set $i=1$ & $e_1 \in E$ s.t. $w_t(e_1)$ is minimal.

For $1 \leq i \leq n-2$, suppose edges e_1, \dots, e_i have been selected.

Choose e_{i+1} in the remaining edges s.t.

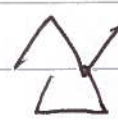
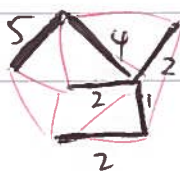
1/ \nexists cycles in the subgraph of G consisting of edges $\{e_1, \dots, e_{i+1}\}$

2/ $w_t(e_{i+1})$ is minimal among edges satisfying 1.

Step 3 $i=i+1$ If $i=n-1$ \square

$i < n-1$, to step 2.

e.g.



4 possibilities

(2)

Thm

$G=(V,E)$ loop-free, wt, conn., undirected

Then \forall spanning tree produced by K's algo. is optimal.

- NOT OBVIOUS! since even at the beginning, it is possible \exists many choice of e_1 & as we see before, \exists many MST.

Proof

By contradiction.

Suppose T is a spanning tree of G produced by K's algo.

Let $E(T) = \{e_1, \dots, e_{n-1}\}$.

Then $\exists T'$, a MST of G s.t. $wt(T') < wt(T)$.

So $\exists 1 \leq r \leq n-1$ s.t. $\{e_1, \dots, e_{r-1}\} \subset E(T')$
but $e_r \notin E(T')$.

Among these MST T'

\rightarrow Choose T' s.t. r reaches maximal.

Let $E(T') = \{e_1, \dots, e_{r-1}, e'_1, \dots, e'_{n-1}\}$.

By K's algorithm, $wt(e'_j) \geq wt(e_r) \forall j \geq r$.

In T' , \exists path connecting the endpoints of $e_r: x-y$,
denote it by $p: x \overset{a_1}{-} x_1 \dots \dots x_{m-1} \overset{a_m}{-} y$. ($a_i \in E(T')$)

Since T is tree, then

$\{a_1, \dots, a_m\} \not\subset E(T)$.

Say $a_k \notin E(T)$ but $a_k \in E(T')$, so $a_k \in \{e'_1, \dots, e'_{n-1}\}$
& $wt(a_k) \geq wt(e_r)$

Let $T'' = T \setminus \{a_k\} \cup \{e_r\}$.

which is also a tree (why?)

& $wt(T'') < wt(T') < wt(T)$

& $E(T'') \cap E(T) = \{e_1, \dots, e_r\}$.

contradiction

\rightarrow to the choice of T' .

③

Idea 2 Build a tree & spanning the tree.

Prim's algo.

Step 1. $i=1$. $\forall v_i \in V$ & $T_i = \{v_i\}$.

Step 2. $1 \leq i \leq n-1$ & we have a tree T_i with i vertices.
(V_i, E_i)

Let e_{i+1} be an edge in the remaining edges s.t.

✓ $T_i \cup \{e_{i+1}\}$ is still a tree

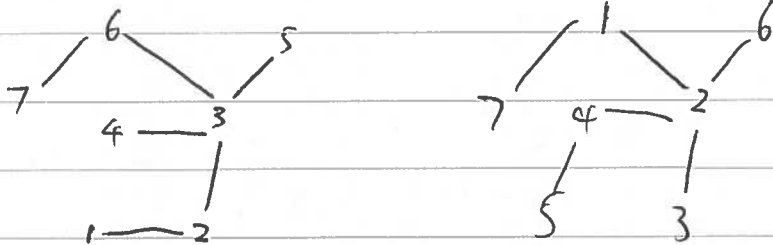
✓ $w(e_{i+1})$ is minimal

$T_{i+1} = T_i \cup \{e_{i+1}\}$

Step 3. $i=i+1$ If $i=n$ \square

If $i < n$ back to Step 2.

e.g. (Note that we can start with \forall vertex)



How to check if e_{i+1} satisfies ✓?

easy: none of its endpoints is in V_i .

exactly

In K's algo. How to check $e_{i+1} \cup \{e_1, \dots, e_i\}$ contains no cycles? Harder.

④

Thm Prim's algor. also produces MST.

Proof. "Similarly"

