EXTRA TASKS

1. Let $T: \mathbb{R}^3 \to \mathbb{R}^3$ be a linear transformation defined by

$$T\left(\begin{bmatrix}1\\0\\0\end{bmatrix}\right) = \begin{bmatrix}1\\-2\\1\end{bmatrix}, \ T\left(\begin{bmatrix}-1\\2\\0\end{bmatrix}\right) = \begin{bmatrix}1\\4\\1\end{bmatrix} \text{ and } T\left(\begin{bmatrix}1\\3\\-1\end{bmatrix}\right) = \begin{bmatrix}3\\1\\5\end{bmatrix}.$$

- i. Find the standard matrix A corresponding to the transformation T.
- ii. Let $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ be the columns of A. Show that the columns of A form an orthogonal set and find the orthogonal projection of the vector $\mathbf{u} = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$ to $\mathrm{Span}\{\mathbf{v}_1, \mathbf{v}_3\}$.

i. The standard matrix
$$A$$
 is given by
$$A = \int T(\vec{e}_1) \qquad T(\vec{e}_2) \qquad T(\vec{e}_3) \int,$$
where $\vec{e}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$, $\vec{e}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$, and $\vec{e}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$.

$$T\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$
,
$$T\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$
,
$$T\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$
,
$$T\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) = -T\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}\right) + 2T\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right)$$

$$\Rightarrow T\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) = \frac{1}{2} T\left(\begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix}\right) + \frac{1}{2} T\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}\right)$$

$$=\frac{1}{2}\begin{bmatrix}1\\4\\1\end{bmatrix}+\frac{1}{2}\begin{bmatrix}1\\-2\\1\end{bmatrix}=\begin{bmatrix}1\\1\\1\end{bmatrix}$$

$$= T\left(\begin{bmatrix} 0 \\ 0 \end{bmatrix}\right) + 3T\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) - T\left(\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}\right)$$

$$\Rightarrow T\left(\begin{bmatrix}0\\0\\1\end{bmatrix}\right) = T\left(\begin{bmatrix}1\\0\\0\end{bmatrix}\right) + 3T\left(\begin{bmatrix}0\\1\\0\end{bmatrix}\right) - T\left(\begin{bmatrix}1\\3\\-1\end{bmatrix}\right)$$

$$= \begin{bmatrix} 1 \\ -\lambda \\ 1 \end{bmatrix} + 3 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 3 \\ 1 \\ 5 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}_{/\!/}$$

So the standard matrix A is

ii. Claim: {Vi, Va, V3 } is an orthogonal set.

We will show that

$$\vec{\nabla}_1 \cdot \vec{\nabla}_2 = \vec{\nabla}_1 \cdot \vec{\nabla}_3 = \vec{\nabla}_2 \cdot \vec{\nabla}_3 = 0$$

We will show that
$$\overrightarrow{V_1} \cdot \overrightarrow{V_2} = \overrightarrow{V_1} \cdot \overrightarrow{V_3} = \overrightarrow{V_2} \cdot \overrightarrow{V_3} = 0.$$

$$\overrightarrow{V_1} \cdot \overrightarrow{V_2} = \begin{bmatrix} 1 \\ -\lambda \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} = 1 - \lambda + 1 = 0 \quad \text{if} \quad \overrightarrow{V_1} \cdot \overrightarrow{V_3} = \begin{bmatrix} 1 \\ -\lambda \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} = 1 + 0 - 1 = 0$$

$$\vec{V}_2 \cdot \vec{V}_3 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} = 1 + 0 - 1 = 0 \cdot \text{Hence}, \text{ the above claim holds.}$$

Let
$$W = Span \{\vec{y}_1, \vec{y}_3\}$$
. Then the orthogonal projection of $\vec{y} = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$ onto W is given by $P_W \vec{y} = \frac{\vec{y}_1 \cdot \vec{y}}{\vec{y}_1 \cdot \vec{y}} \vec{y}_1 + \frac{\vec{y}_3 \cdot \vec{y}_3}{\vec{y}_3 \cdot \vec{y}_3}$.

$$\Rightarrow \overrightarrow{V}_1 \cdot \overrightarrow{V}_1 = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} = 6 \quad \text{and} \quad \overrightarrow{V}_1 \cdot \overrightarrow{V}_1 = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix} = 3$$

$$\Rightarrow \vec{3} \cdot \vec{3} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = 2 \quad \text{and} \quad \vec{3} \cdot \vec{1} = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix} = -1$$

2. Show in each of the following cases whether or not the subsets of the given vector spaces are subspaces.

i.
$$U_1 = \left\{ \begin{bmatrix} a \\ b \end{bmatrix} \mid 2a - 3b = 0 \text{ and } a, b \in \mathbb{R} \right\} \subseteq \mathbb{R}^2$$

ii. $U_2 = \left\{ \begin{bmatrix} a & 0 \\ c & d \end{bmatrix} \mid ad = 0 \text{ and } a, c, d \in \mathbb{R} \right\} \subseteq M_{2 \times 2}$, where $M_{2 \times 2}$ is the vector space of all 2×2 matrices.

iii.
$$U_3^m = \left\{ \begin{bmatrix} 6s - 4t \\ 2s + t \\ t - m \end{bmatrix} \mid s, t \in \mathbb{R} \right\} \subseteq \mathbb{R}^3$$

a. when m=0 and

b. when m=1.

$$\frac{SOLUTION}{\text{let}} \quad V_1 = \left\{ \begin{bmatrix} 9 \\ b \end{bmatrix} \mid 2a-3b=0 \text{ and } a,b \in \mathbb{R}^3 \right\} \subseteq \mathbb{R}^3.$$

•
$$\begin{bmatrix} 0 \\ 0 \end{bmatrix} \in \mathcal{V}$$
, since $2(0) - 3(0) = 0$ and $0 \in \mathbb{R}$.

• Let
$$\vec{X}_1 = \begin{bmatrix} q_1 \\ b_1 \end{bmatrix}$$
 and $\vec{X}_2 = \begin{bmatrix} q_2 \\ b_2 \end{bmatrix}$ be in V_1 . So

$$2a_1 - 3b_1 = 0$$
 and $2a_2 - 3b_2 = 0$.

$$\vec{\chi}_{1} + \vec{\chi}_{2} = \begin{bmatrix} a_{1} + a_{2} \\ b_{1} + b_{2} \end{bmatrix} = \begin{bmatrix} a_{1} + a_{2} \\ b_{1} + b_{2} \end{bmatrix} = 2(a_{1} + a_{2}) - 3(b_{1} + b_{2}) = 2(a_{1} + a_{2}) - 3(b_{1} + b_{2}) = 0$$

$$\Rightarrow 2(a_{1} + a_{2}) - 3(b_{1} + b_{2}) = 0$$

• Let
$$\vec{X} = \begin{bmatrix} q \\ b \end{bmatrix} \in V$$
, and $k \in \mathbb{R}$. Then $2q - 3b = 0$.

$$C\vec{\lambda} = \begin{bmatrix} ca \\ cb \end{bmatrix} \cdot \Rightarrow 2(ca) - 3(cb) = c(2a-3b) = 0$$

$$\Rightarrow c\vec{x} \in \mathcal{V}_1.$$

ii.
$$V_2 = \left\{ \begin{bmatrix} a & 0 \\ c & d \end{bmatrix} \mid ad = 0 \text{ and } a, c, d \in \mathbb{R} \right\}.$$

- Clearly, $\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \in \mathcal{V}_{\lambda}$ since ad = 0 holds.
- U_2 is not closed under addition. We give a counterexample: Let $A_1 = \begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix}$ and $A_2 = \begin{bmatrix} 0 & 0 \\ 0 & -1 \end{bmatrix}$. Clearly, $A_1 \in U_2$ and

$$A_{2} \in V_{2}$$
 since $(0)(-1) = 0$ end $(2)(0) = 0$. But
$$A_{1} + A_{2} = \begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix}$$
 and $2(-1) \neq 0$.

Hence U2 is NOT a subspace of M2x2.

$$\bigcup_{3}^{0} = \left\{ \begin{bmatrix} 6s - 4t \\ as + t \end{bmatrix} \mid s, t \in \mathbb{R} \right\}$$

$$= \begin{cases} 6S - 4t \\ 2S + t \\ t \end{cases} = \begin{cases} 6S \\ 2S \\ 0 \end{cases} + \begin{bmatrix} -4t \\ t \\ t \end{cases} = S \begin{bmatrix} 6 \\ 2 \\ 0 \end{bmatrix} + t \begin{bmatrix} -4 \\ 1 \\ 1 \end{cases}, \quad S, t \in \mathbb{R}.$$

$$S_0$$
 V_3° is $Span \left\{ \begin{bmatrix} 6 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} -4 \\ 1 \\ 1 \end{bmatrix} \right\}$ and S_0 V_3° is a subspace of \mathbb{R}^3 .

$$\bigcup_{3}^{1} = \left\{ \begin{bmatrix} 6s - 4t \\ as + t \\ t - 1 \end{bmatrix} \mid t, s \in \mathbb{R} \right\}.$$

Claim: The zero vector
$$\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$
 is not in V_3 . So consider

$$\Rightarrow \begin{bmatrix} 6S - 4t \\ 2S + t \\ t - 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 6 & -4 \\ 2 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 6 & -4 \\ 0 & \frac{7}{3} \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

Since the system has ND solution, it implies that
$$\begin{bmatrix} 0 \\ 0 \end{bmatrix} \notin \mathcal{V}_3$$
.

$$V_3^1$$
 is NOT a subspace of \mathbb{R}^3 .

3. Let $C[0,\pi/2]$ be the vector space of continuous functions defined on $[0,\pi/2]$ with inner product

$$\langle f, g \rangle = \int_0^{\frac{\pi}{2}} f(t)g(t) dt,$$

where $f, g \in C[0, \pi/2]$. Let $W = \text{Span}\{1, \sin t\}$.

- i. Is the set $\{1, \sin t\}$ an orthogonal set? Justify your answer.
- ii. Find an orthogonal basis for W.

ii. Using the Gram-Schmidt orthogonalization process we will change of, gy to of hi, hay such that h, and ha are

orthogonal.

Let
$$h,(t) = f(t) = 1$$
.

$$\Rightarrow h_{\lambda}(t) = g(t) - P_{h_{\lambda}(t)}g(t)$$
, where $P_{h_{\lambda}}g(t)$ is the projection of

g onto
$$h_1 = f$$
.

$$\int_{h_{i}(t)}^{g} g(t) = \frac{\langle h_{i}, g \rangle}{\langle h_{i}, h_{i} \rangle} h_{i} = \frac{\langle f, g \rangle}{\langle f, f \rangle} f.$$

$$\Rightarrow \langle f, f \rangle = \int_0^{\pi/2} dt = \int_0^{\pi/2} dt = \pi/2$$

$$P_{h_1}g = \frac{1}{\pi/2}(1) = \frac{2}{\pi} \quad \text{and} \quad |h_2(t)| = \sin t - \frac{2}{\pi}$$

$$\langle h_{11}h_{2}\rangle = \int_{0}^{\sqrt{3}} (\sin t - \frac{2}{\pi}) dt = \int_{0}^{\sqrt{3}} \sin t dt - \frac{2}{\pi} \int_{0}^{\sqrt{3}} dt$$

$$= 1 - \frac{2}{\pi} (\sqrt{3}) = 0.$$

Hence, the set $\{1, \sin t - \frac{2}{\pi} \}$ is an orthogonal basis for W.

4. Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be the linear transformation defined by

$$T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} 2x_1 - 3x_2 \\ -6x_1 + 9x_2 \end{bmatrix}.$$

- i. Is T injective?
- ii. Is T surjective?

$$\begin{array}{c}
SOLUTION \\
-6x_1 + 9x_2
\end{array} =
\begin{bmatrix}
2 - 3 \\
-6 - 9
\end{bmatrix}
\begin{bmatrix}
x_1 \\
x_2
\end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 2 & -3 \\ -6 & 9 \end{bmatrix} \sim \begin{bmatrix} 2 & -3 \\ 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & -\frac{3}{2} \\ 0 & 0 \end{bmatrix}.$$

Col
$$A = Span \left\{ \begin{bmatrix} 2 \\ -6 \end{bmatrix} \right\} \neq \mathbb{R}^2$$
 i.e. $Im I \neq \mathbb{R}^2$.

Nyl A = Span
$$\{\begin{bmatrix} 3\\ 2 \end{bmatrix}\}$$
 \neq $\{\begin{bmatrix} 0\\ 0 \end{bmatrix}\}$. i.e. $ker i \neq \{\vec{0}\}$.

5. Let $S: \mathbb{R}^3 \to \mathbb{R}^2$ be the linear transformation defined by

$$S\left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}\right) = \begin{bmatrix} x_1 + x_2 + 2x_3 \\ 2x_1 + x_2 + x_3 \end{bmatrix}.$$

- i. Is S injective?
- ii. Is S surjective?

$$\int \left(\begin{bmatrix} X_1 \\ X_2 \\ X_3 \end{bmatrix} \right) = \begin{bmatrix} X_1 + X_2 + 2X_3 \\ 2X_1 + X_2 + X_3 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 1 \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \\ X_3 \end{bmatrix}$$

SOLUTION

$$\Rightarrow \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 2 \\ 0 & -1 & -3 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 3 \end{bmatrix}$$

$$\text{fol } A = \text{Span} \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\} = \mathbb{R}^2 \quad \text{i.e.} \quad \hat{I} = \mathbb{R}^2$$

$$\text{Nul } A = \text{Span} \left\{ \begin{bmatrix} 1 \\ -3 \end{bmatrix} \right\} \cdot i \cdot e \cdot \text{ Ker } S = \left\{ t \begin{bmatrix} 1 \\ -3 \end{bmatrix} \right\} t \in \mathbb{R} \right\} \neq \left\{ \vec{0} \right\}.$$

ii.
$$S$$
 is surjective since $\widehat{I}_m S = \mathbb{R}^2$.

6. Find the general solution of the system

$$(i-1)x_1$$
 $-4x_2$ = 4
 ix_1 $-2ix_2$ $+(2i+1)x_3$ = $i+1$
 $(3i+1)x_1$ $+(2i-1)x_3$ = 5.

SOLUTION

The matrix equation is given by
$$\begin{bmatrix}
i-1 & -4 & 0 \\
i & -2i & 1+2i \\
1+3i & 0 & -1+2i
\end{bmatrix}
\begin{bmatrix}
x_1 \\
x_2 \\
x_3
\end{bmatrix}
=
\begin{bmatrix}
4 \\
i+1 \\
5
\end{bmatrix}$$

Consider the augmented matrix and find the reduced Echelon of the above matrix.

$$\begin{bmatrix} i-1 & -4 & 0 & 4 \\ i & -2i & 1+2i & 1+i \\ 1+3i & 0 & -1+2i & 5 \end{bmatrix} \xrightarrow{1} \begin{bmatrix} 1 & 2+2i & 0 & -2-2i \\ i-1 & -2i & 1+2i & 1+i \\ 1+3i & 0 & -1+2i & 5 \end{bmatrix}$$

$$\begin{bmatrix}
1 & 2+2i & 0 & | -(2+2i) \\
0 & 2-4i & 1+2i & | -1+3i
\end{bmatrix}$$

$$\begin{bmatrix}
-1 & 2+2i & 0 & | -(2+2i) \\
3+2i & 7 & 0 & 2-4i & 1+2i & | -1+3i
\end{bmatrix}$$

$$\begin{bmatrix}
0 & 2-4i & 1+2i & | -1+3i \\
0 & 0 & | -1-1-3i
\end{bmatrix}$$

$$\begin{cases} x_1 = 1 - i \\ x_2 = -1 + \frac{i}{2} \\ x_3 = -1 \end{cases}$$